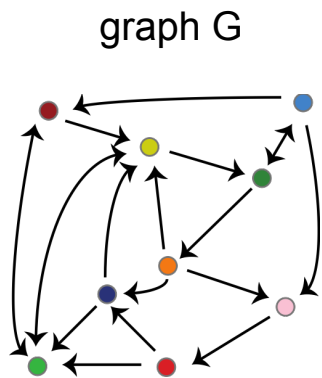
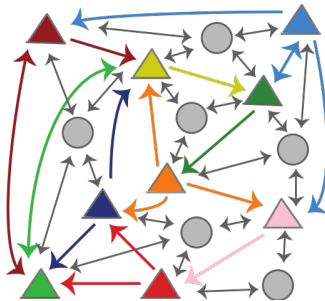


So far, everything we have done for CTLNs/gCTLNs has assumed negative (**inhibitory**) weights on the W matrix.



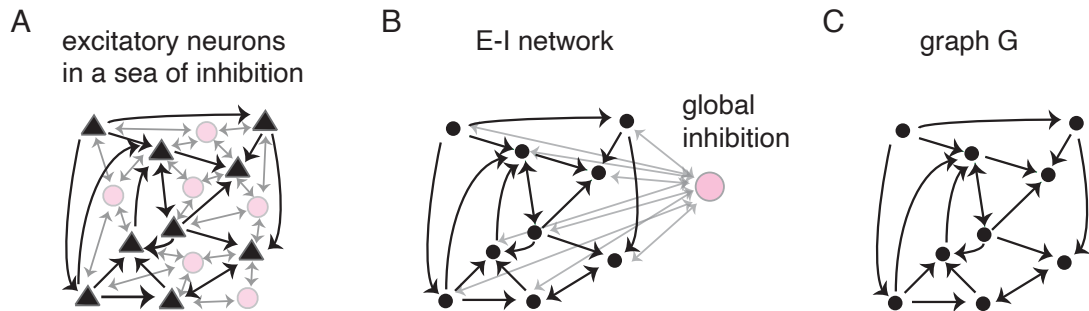
Idea: network of excitatory and inhibitory cells



The **gCTLN** is defined by a **graph G** and two vectors of parameters:

$$W_{ij} = \begin{cases} -1 + \varepsilon_j & \text{if } j \rightarrow i, \text{ weak inhibition} \\ -1 - \delta_j & \text{if } j \not\rightarrow i, \text{ strong inhibition} \\ 0 & \text{if } i = j. \end{cases}$$

E-I TLNs from graphs



$$\frac{dx_i}{dt} = -x_i + \left[\sum_{j=1}^n W_{ij}x_j + W_{iI}(x_I - W_{II}x_i) + b_i \right]_+, \quad i = 1, \dots, n,$$

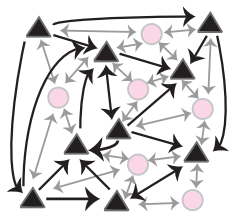
$$\frac{dx_I}{dt} = \frac{1}{\tau_I} \left(-x_I + \left[\sum_{j=1}^n W_{Ij}x_j + b_I \right]_+ \right).$$

$$W_{ij} = \begin{cases} a_j & \text{if } j \rightarrow i \text{ in } G, \\ 0 & \text{if } j \not\rightarrow i \text{ in } G, \\ 0 & \text{if } i = j, \end{cases} \quad \text{and} \quad \begin{aligned} W_{Ij} &= c_j, \\ W_{iI} &= -1, \\ W_{II} &= 0. \end{aligned}$$

E-I TLNs from graphs

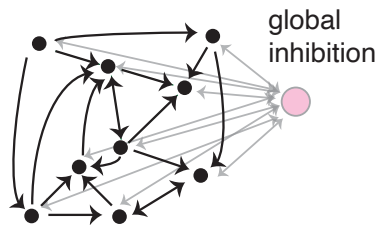
A

excitatory neurons
in a sea of inhibition



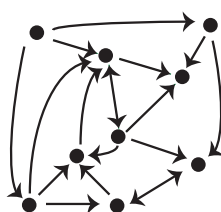
B

E-I network



C

graph G

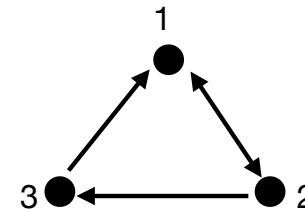


$$\frac{dx_i}{dt} = -x_i + \left[\sum_{j=1}^n W_{ij}x_j + W_{iI}(x_I - W_{II}x_i) + b_i \right]_+, \quad i = 1, \dots, n,$$

$$\frac{dx_I}{dt} = \frac{1}{\tau_I} \left(-x_I + \left[\sum_{j=1}^n W_{Ij}x_j + b_I \right]_+ \right).$$

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Example G:



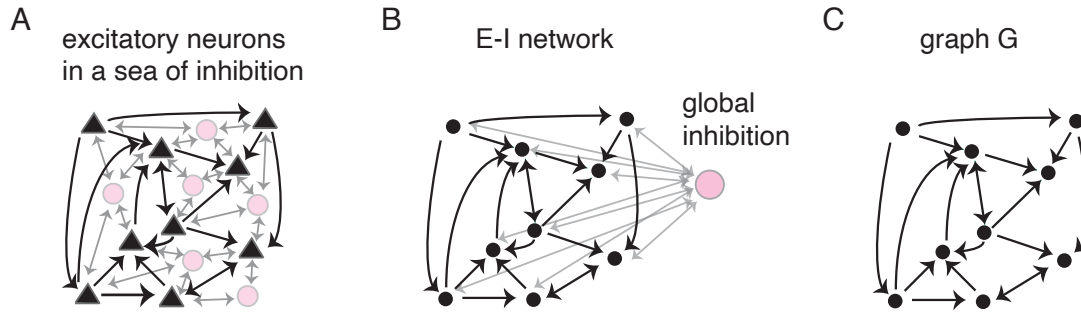
W for E-I TLN

$$W = \begin{pmatrix} 0 & a_2 & a_3 & -1 \\ a_1 & 0 & 0 & -1 \\ 0 & a_2 & 0 & -1 \\ c_1 & c_2 & c_3 & 0 \end{pmatrix}$$

W for gCTLN

$$W = \begin{pmatrix} 0 & -1 + \varepsilon_2 & -1 + \varepsilon_3 \\ -1 + \varepsilon_1 & 0 & -1 - \delta_3 \\ -1 - \delta_1 & -1 + \varepsilon_2 & 0 \end{pmatrix}$$

There is a mapping from E-I TLNs to gCTLNs that preserves fixed points



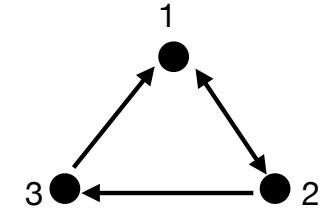
$$\frac{dx_i}{dt} = -x_i + \left[\sum_{j=1}^n W_{ij}x_j + \boxed{W_{iI}(x_I - W_{Ii}x_i)} + b_i \right]_+, \quad i = 1, \dots, n,$$

$$\frac{dx_I}{dt} = \frac{1}{\tau_I} \left(-x_I + \left[\sum_{j=1}^n W_{Ij}x_j + b_I \right]_+ \right).$$

Parameter mapping
to get the same
fixed points:

$$\begin{aligned} \varepsilon_j &= 1 + a_j - c_j, \\ \delta_j &= c_j - 1. \end{aligned}$$

Example G:



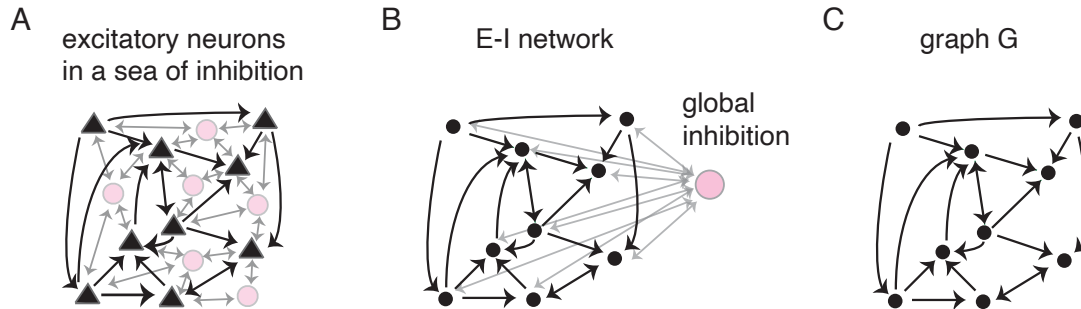
W for E-I TLN

$$W = \begin{pmatrix} 0 & a_2 & a_3 & -1 \\ a_1 & 0 & 0 & -1 \\ 0 & a_2 & 0 & -1 \\ c_1 & c_2 & c_3 & 0 \end{pmatrix}$$

W for gCTLN

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There is a mapping from E-I TLNs to gCTLNs that preserves fixed points



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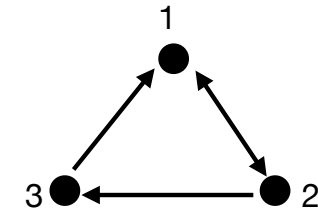
$$\frac{dx_I}{dt} = \boxed{\frac{1}{\tau_I}} \left(-x_I + \left[\sum_{j=1}^n W_{Ij}x_j + b_I \right]_+ \right).$$

Parameter mapping
to get the same
fixed points:

$$\begin{aligned} \varepsilon_j &= 1 + a_j - c_j, \\ \delta_j &= c_j - 1. \end{aligned}$$

The mapping says nothing about the timescale of inhibition!

Example G:



W for E-I TLN

$$W = \begin{pmatrix} 0 & a_2 & a_3 & -1 \\ a_1 & 0 & 0 & -1 \\ 0 & a_2 & 0 & -1 \\ c_1 & c_2 & c_3 & 0 \end{pmatrix}$$

W for gCTLN

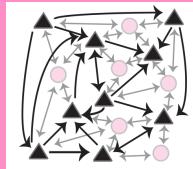
$$W = \begin{pmatrix} 0 & -1 + \varepsilon_2 & -1 + \varepsilon_3 \\ -1 + \varepsilon_1 & 0 & -1 - \delta_3 \\ -1 - \delta_1 & -1 + \varepsilon_2 & 0 \end{pmatrix}$$

TLNs, CTLNs, and gCTLNs ... and E-I TLNs from graphs

all recurrent network models

TLNs

E-I TLNs
from graphs

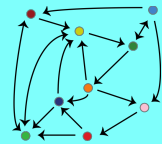


competitive TLNs

CTLNs

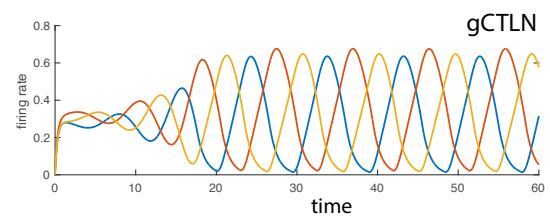
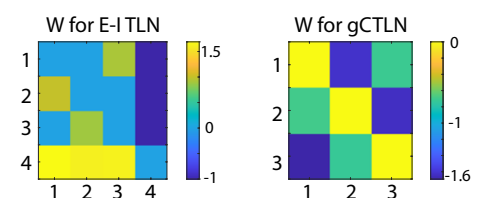
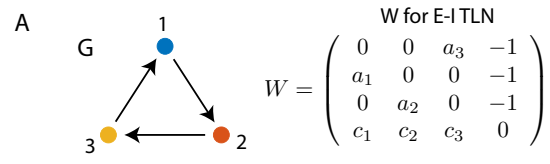
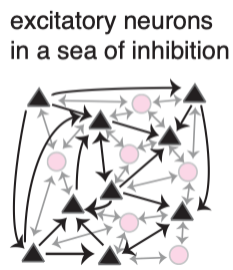


gCTLNs

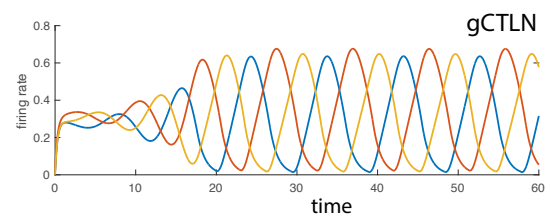
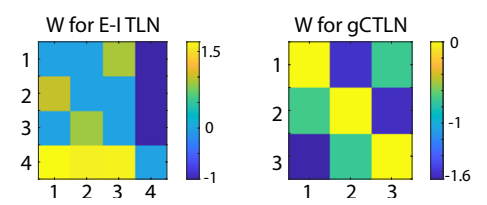
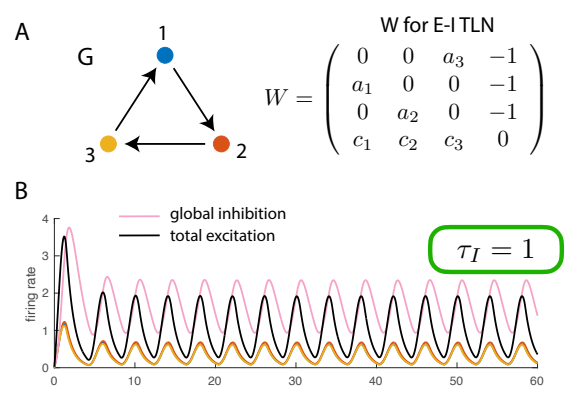
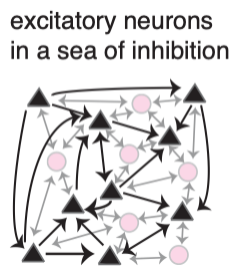


linear
models

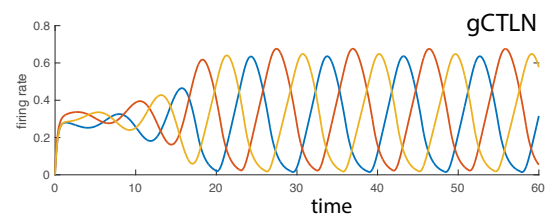
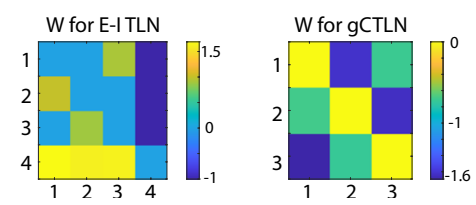
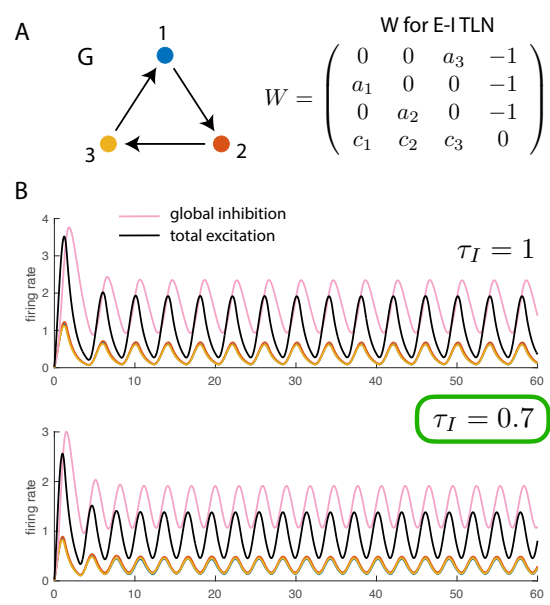
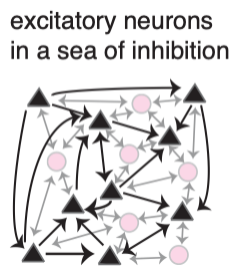
Beyond fixed points: do E-I TLNs produce similar dynamics to gCTLNs?



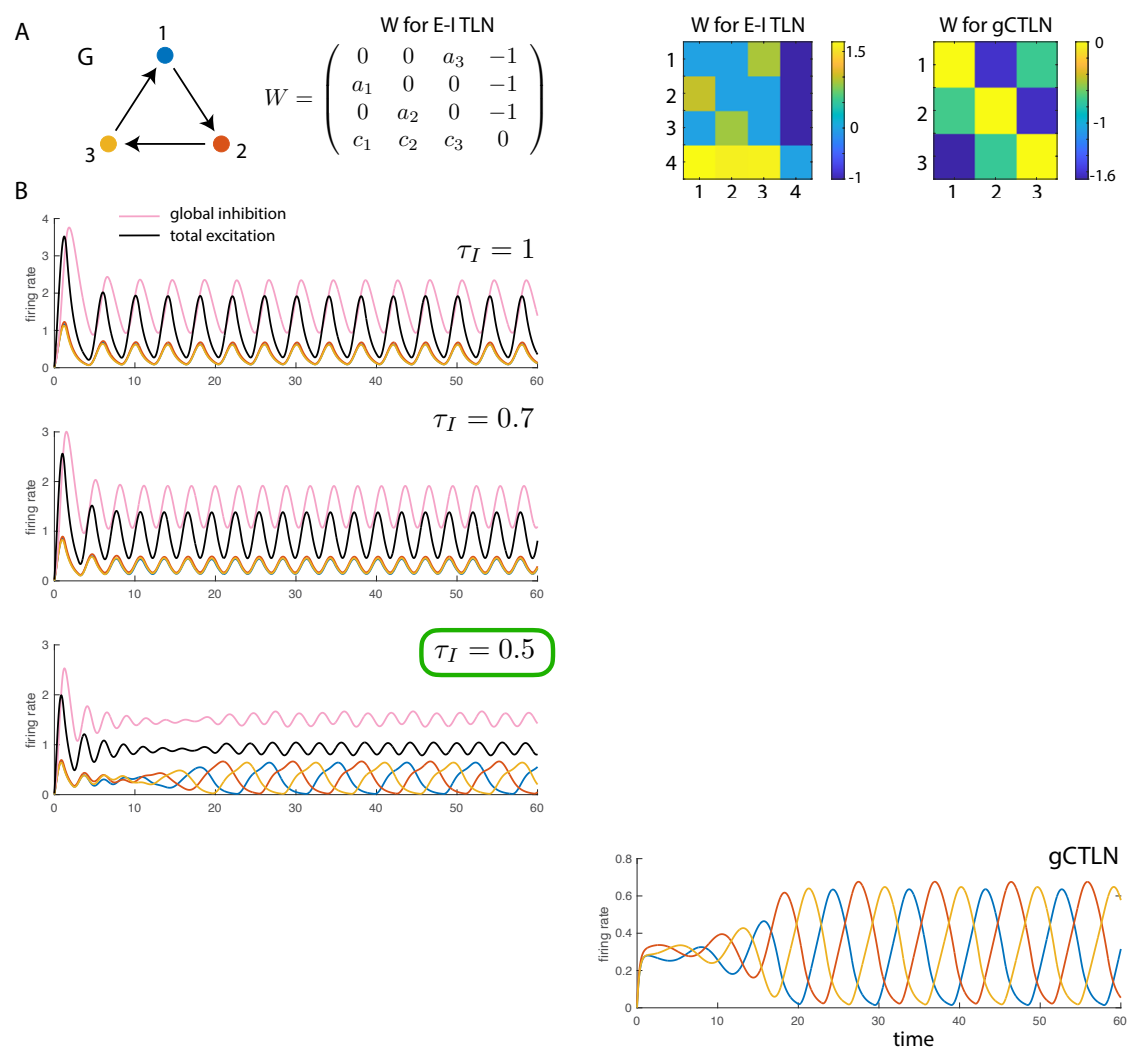
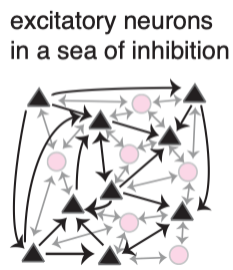
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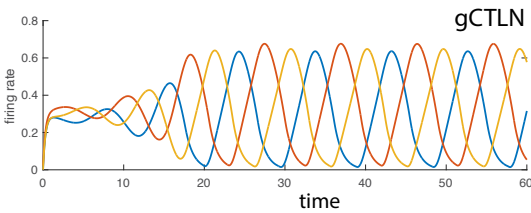
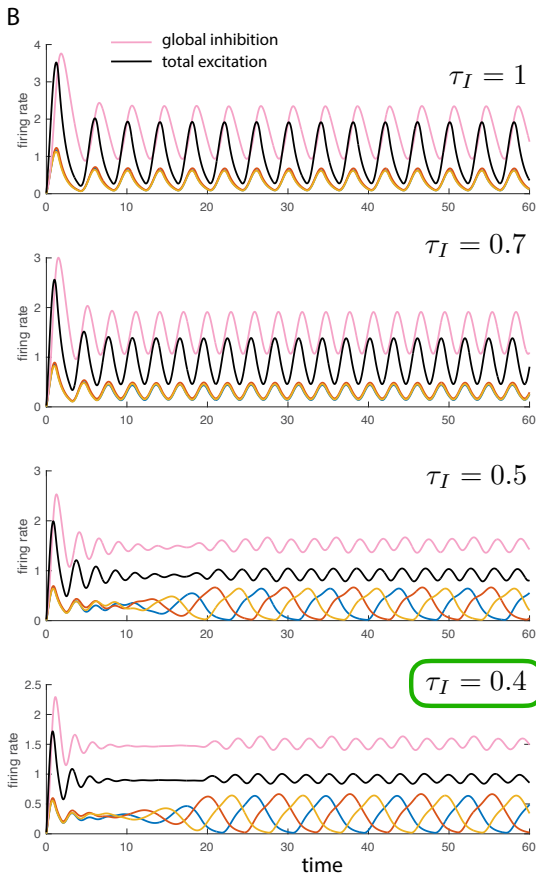
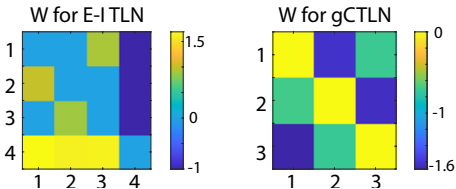
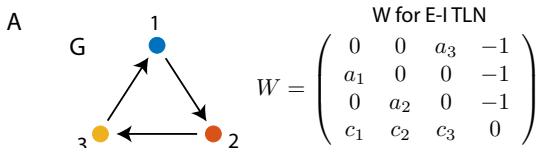
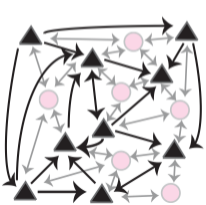


Beyond fixed points: do E-I TLNs produce similar dynamics to gCTLNs?



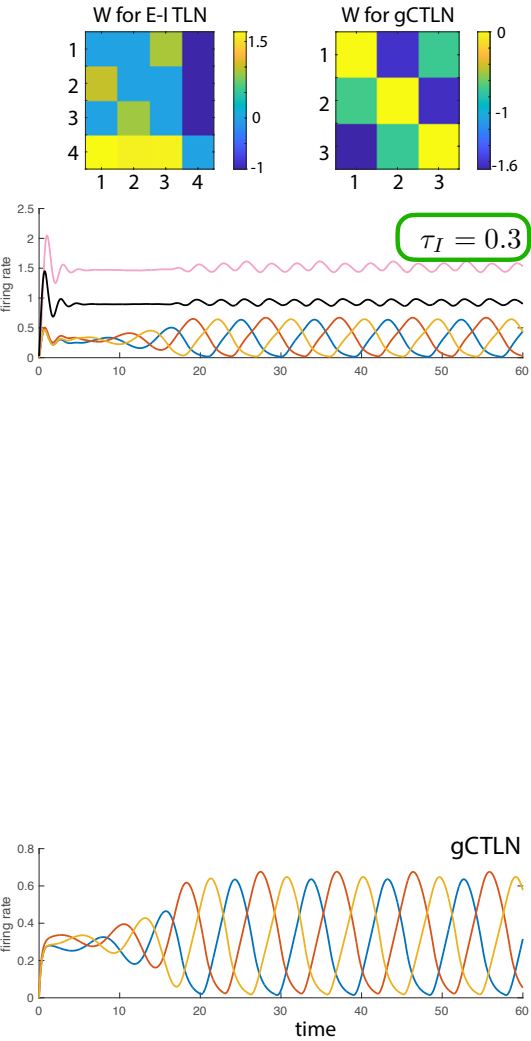
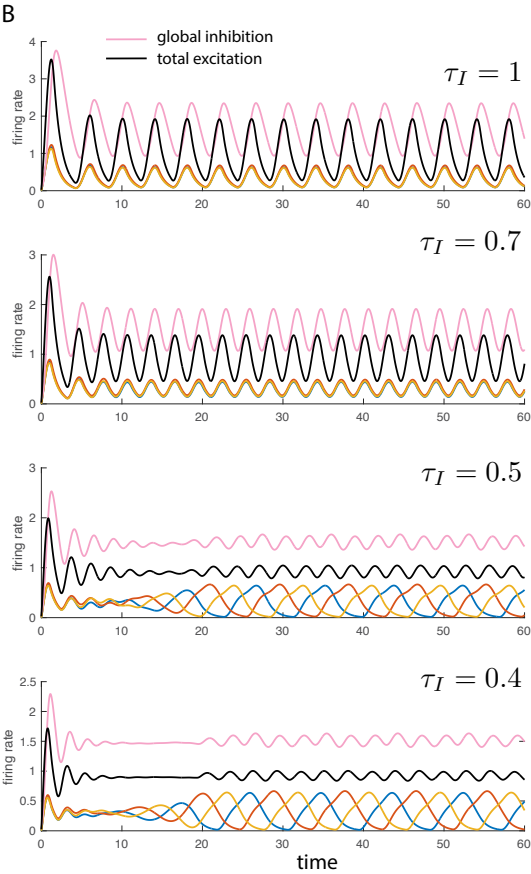
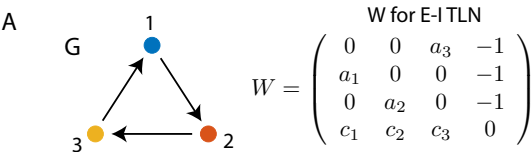
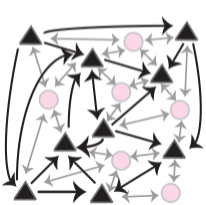
Beyond fixed points: do E-I TLNs produce similar dynamics to gCTLNs?

excitatory neurons
in a sea of inhibition



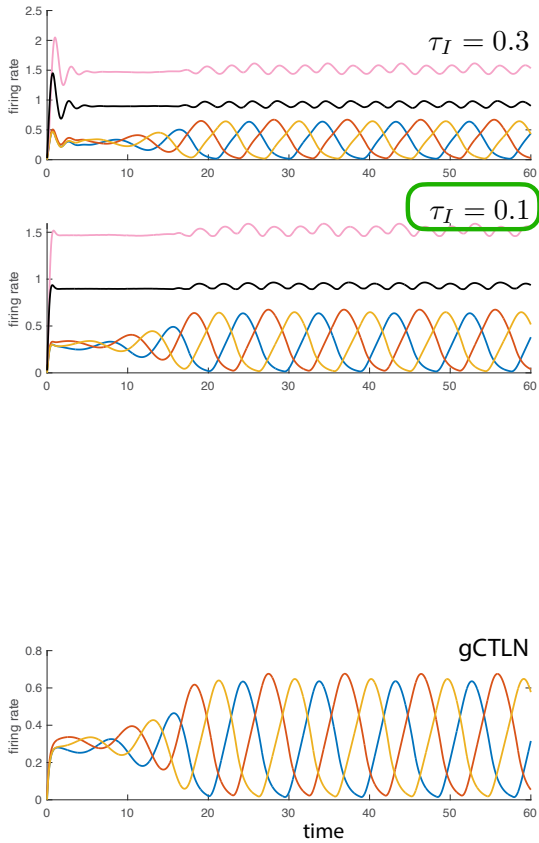
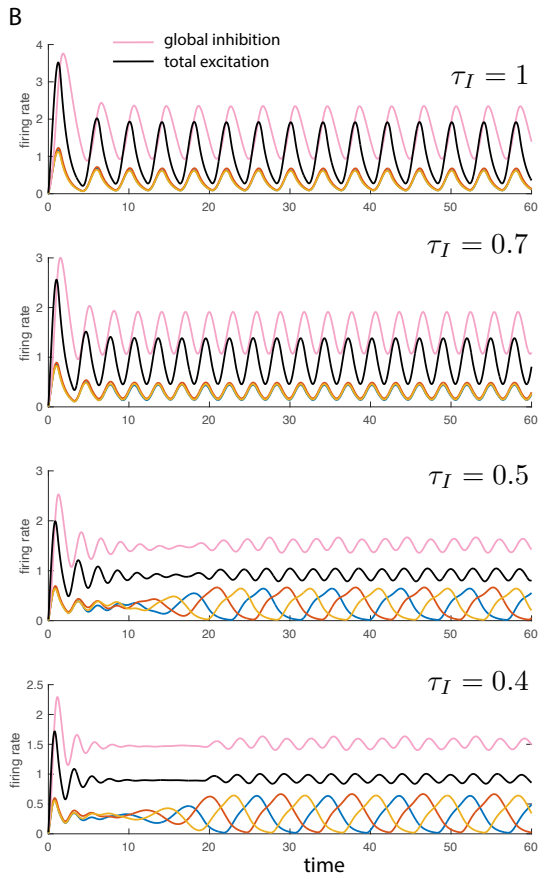
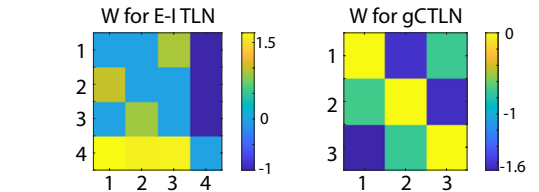
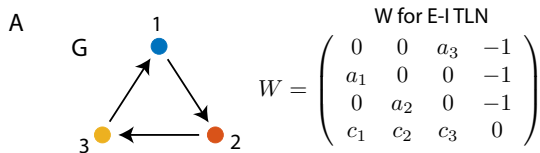
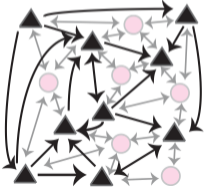
Beyond fixed points: do E-I TLNs produce similar dynamics to gCTLNs?

excitatory neurons
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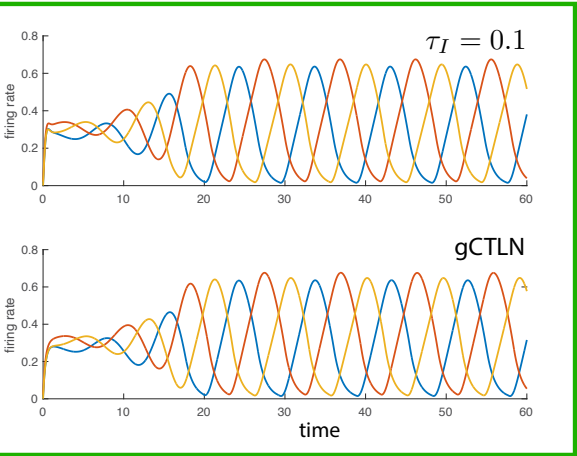
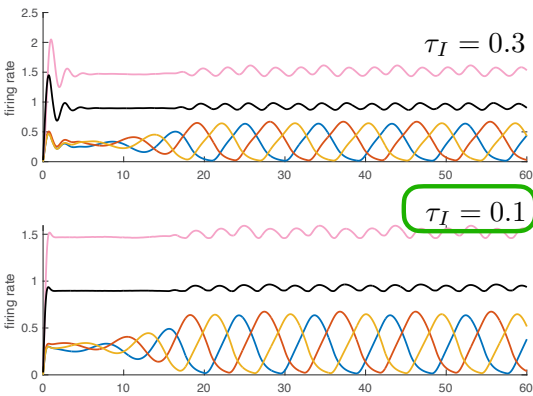
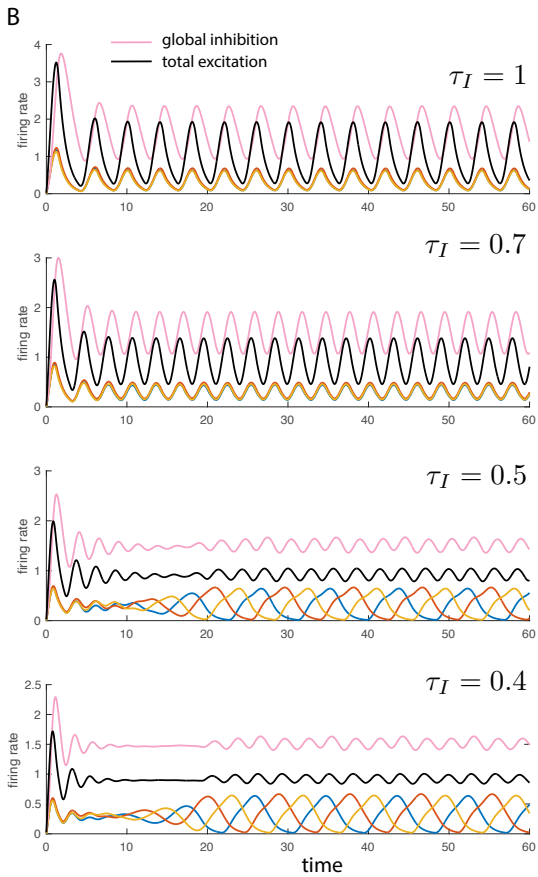
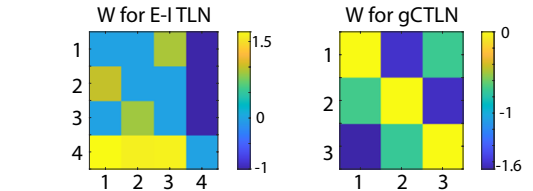
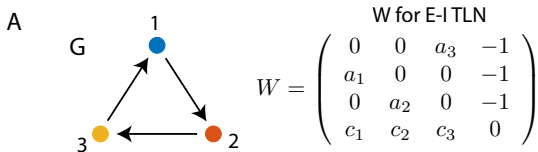
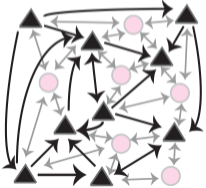
Beyond fixed points: do E-I TLNs produce similar dynamics to gCTLNs?

excitatory neurons
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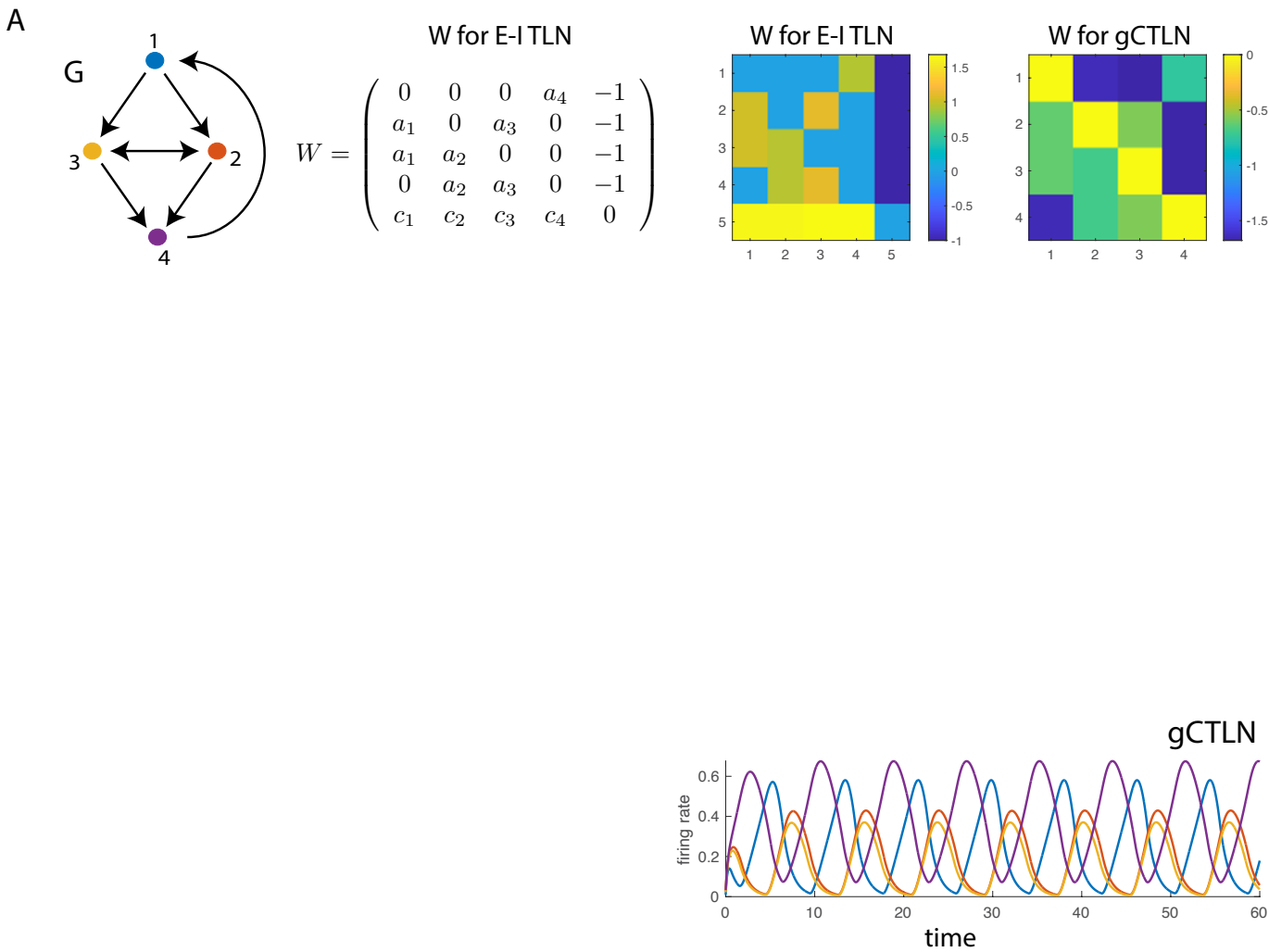


Beyond fixed points: do E-I TLNs produce similar dynamics to gCTLNs?

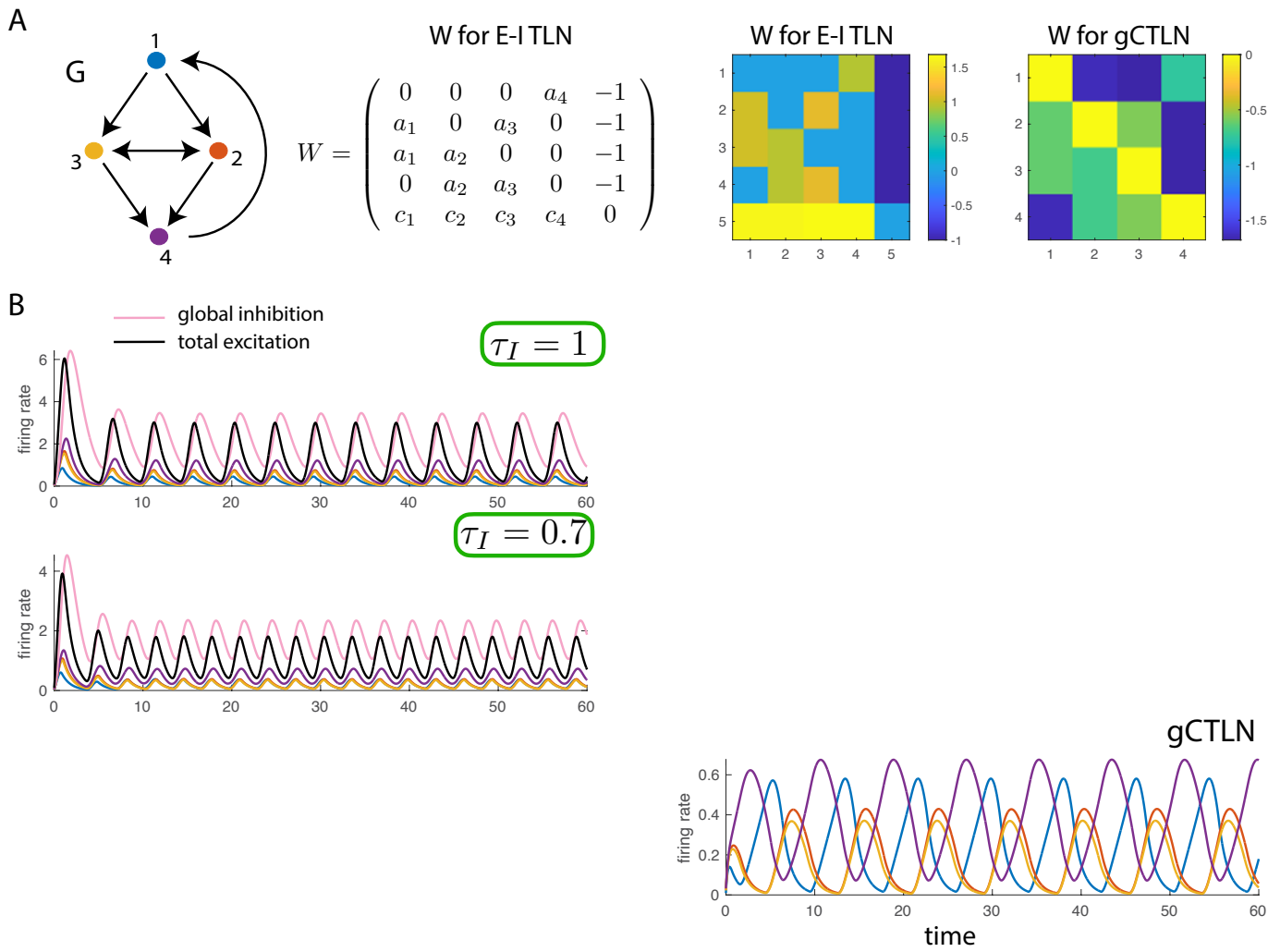
excitatory neurons
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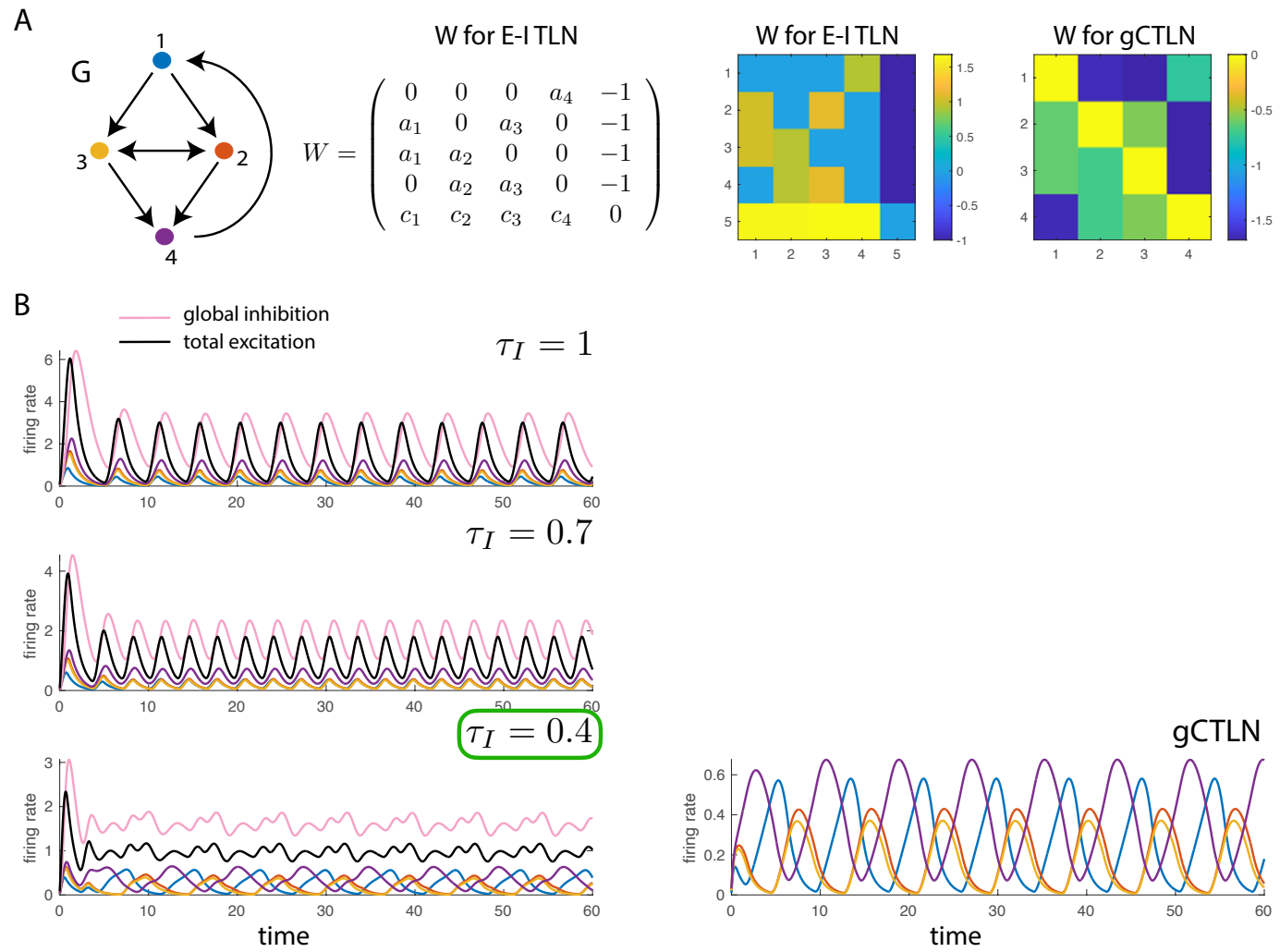
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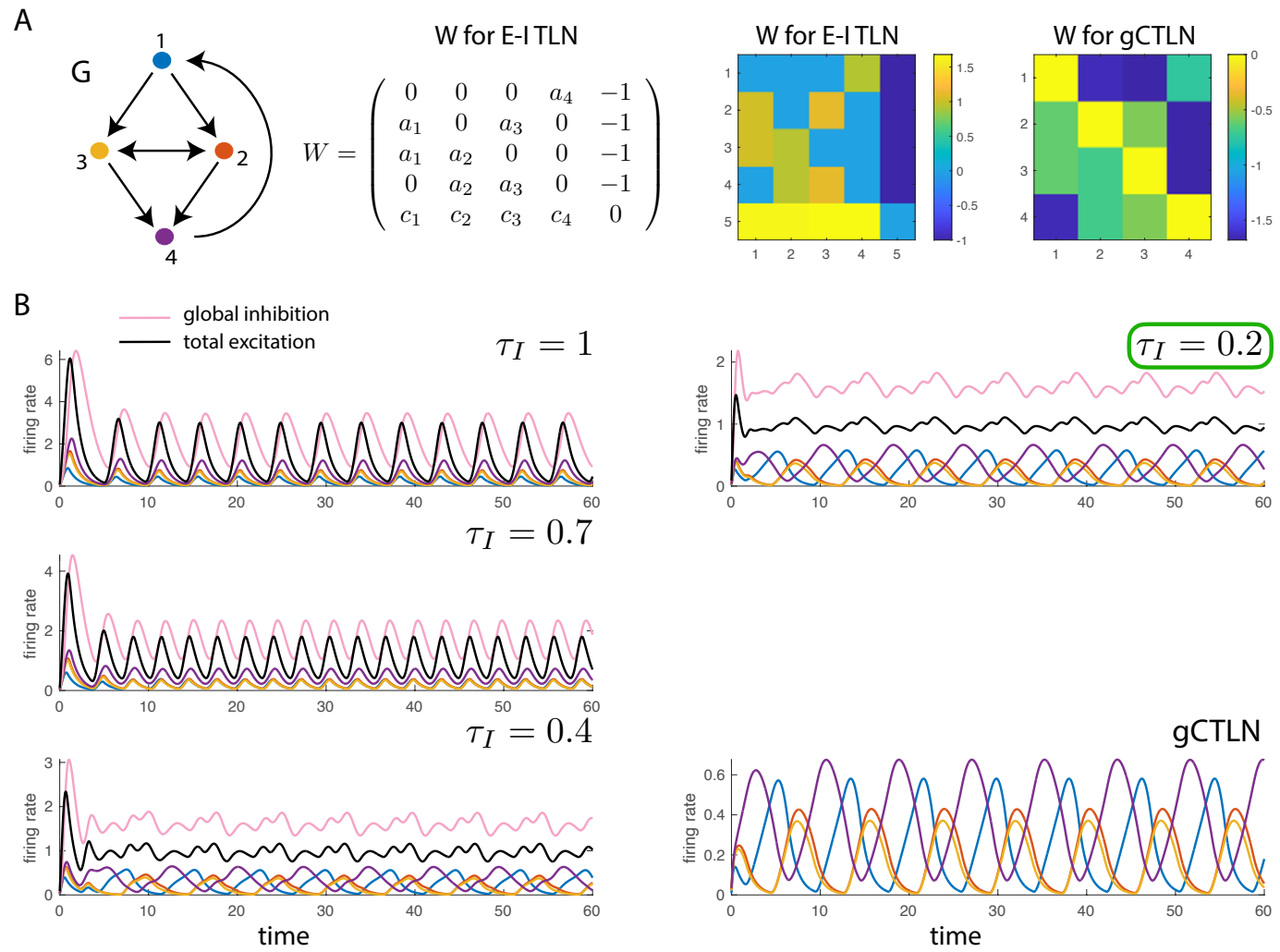
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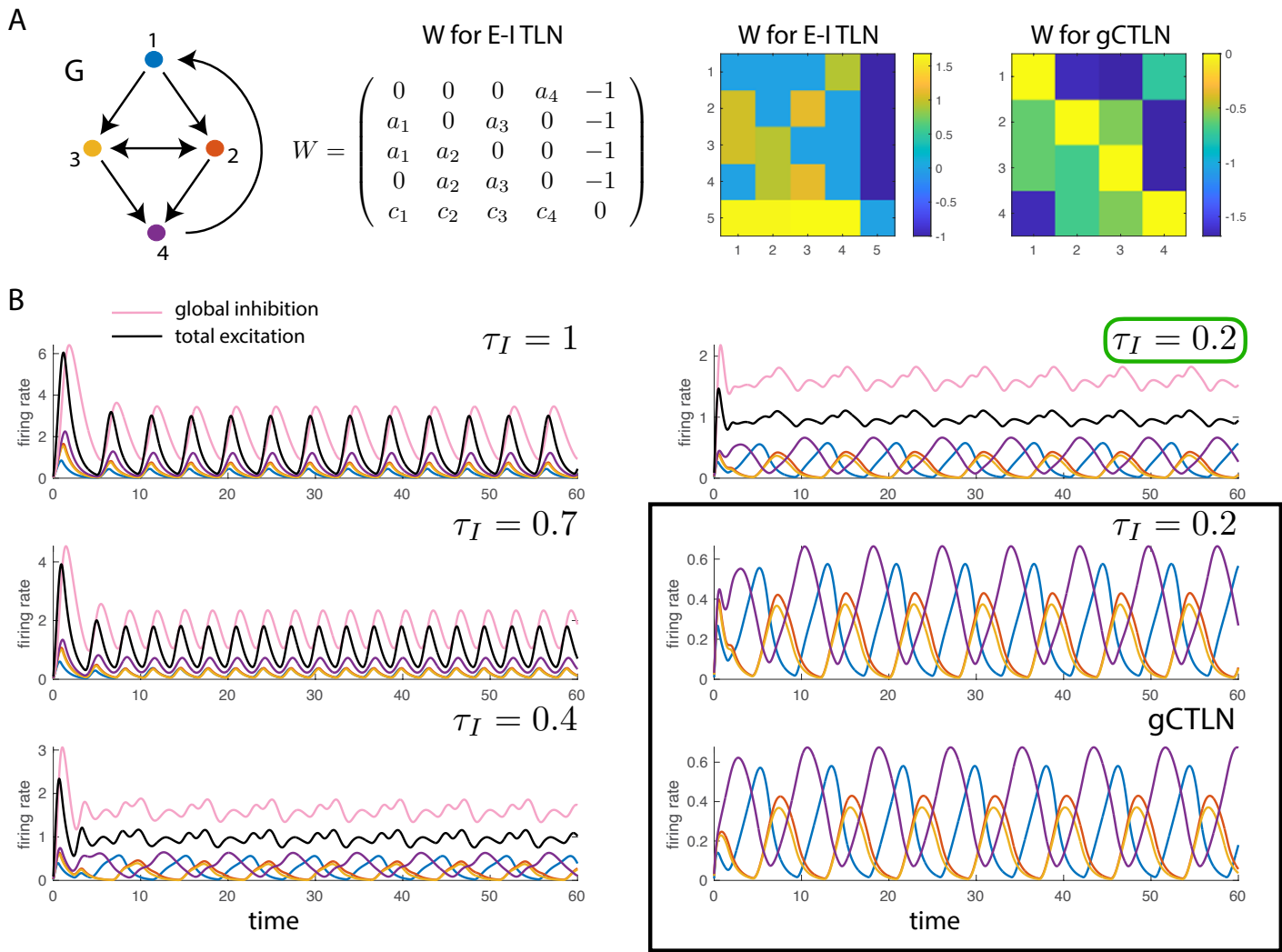
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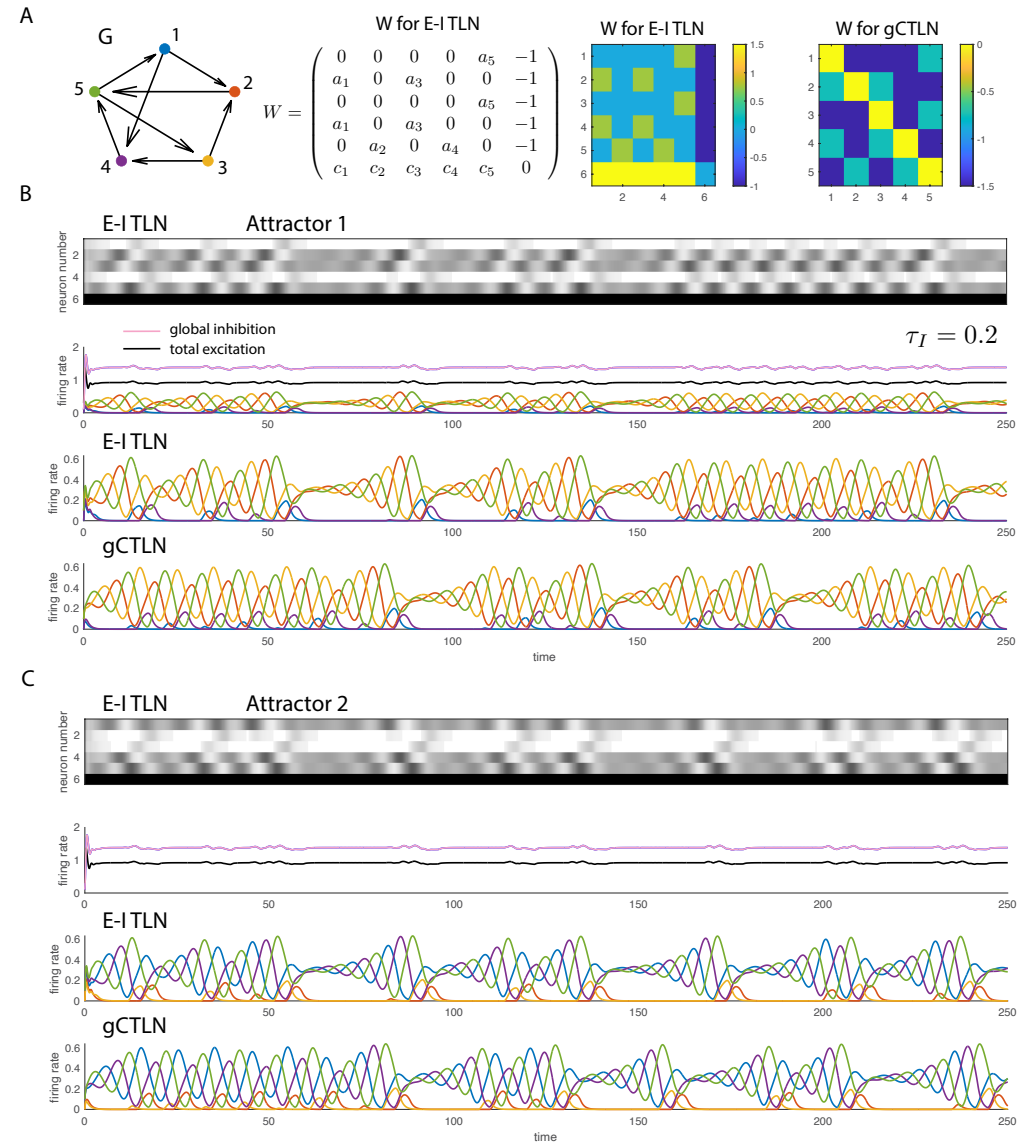
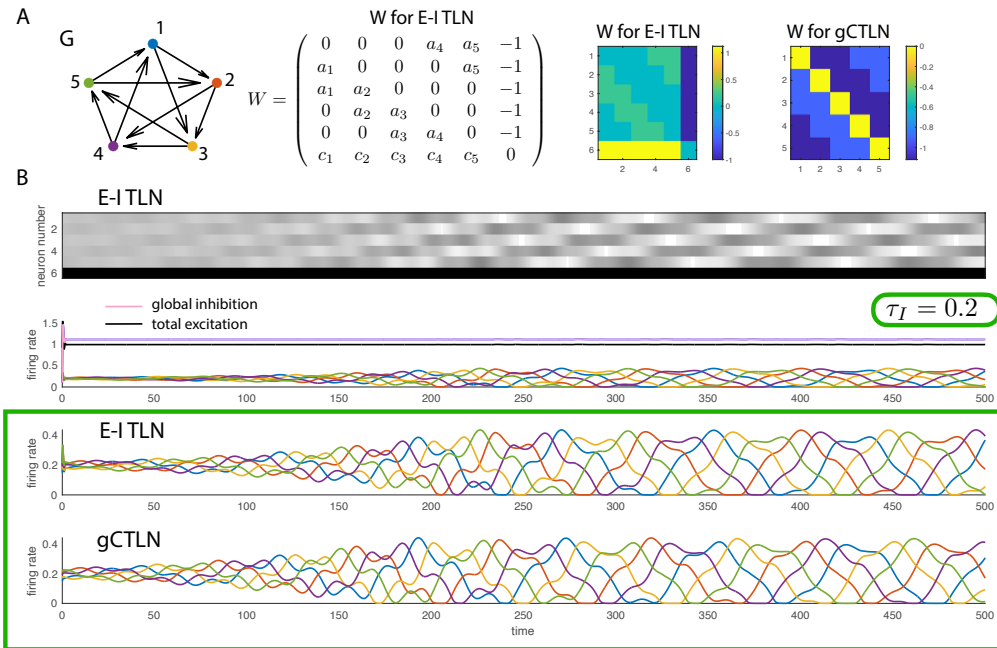
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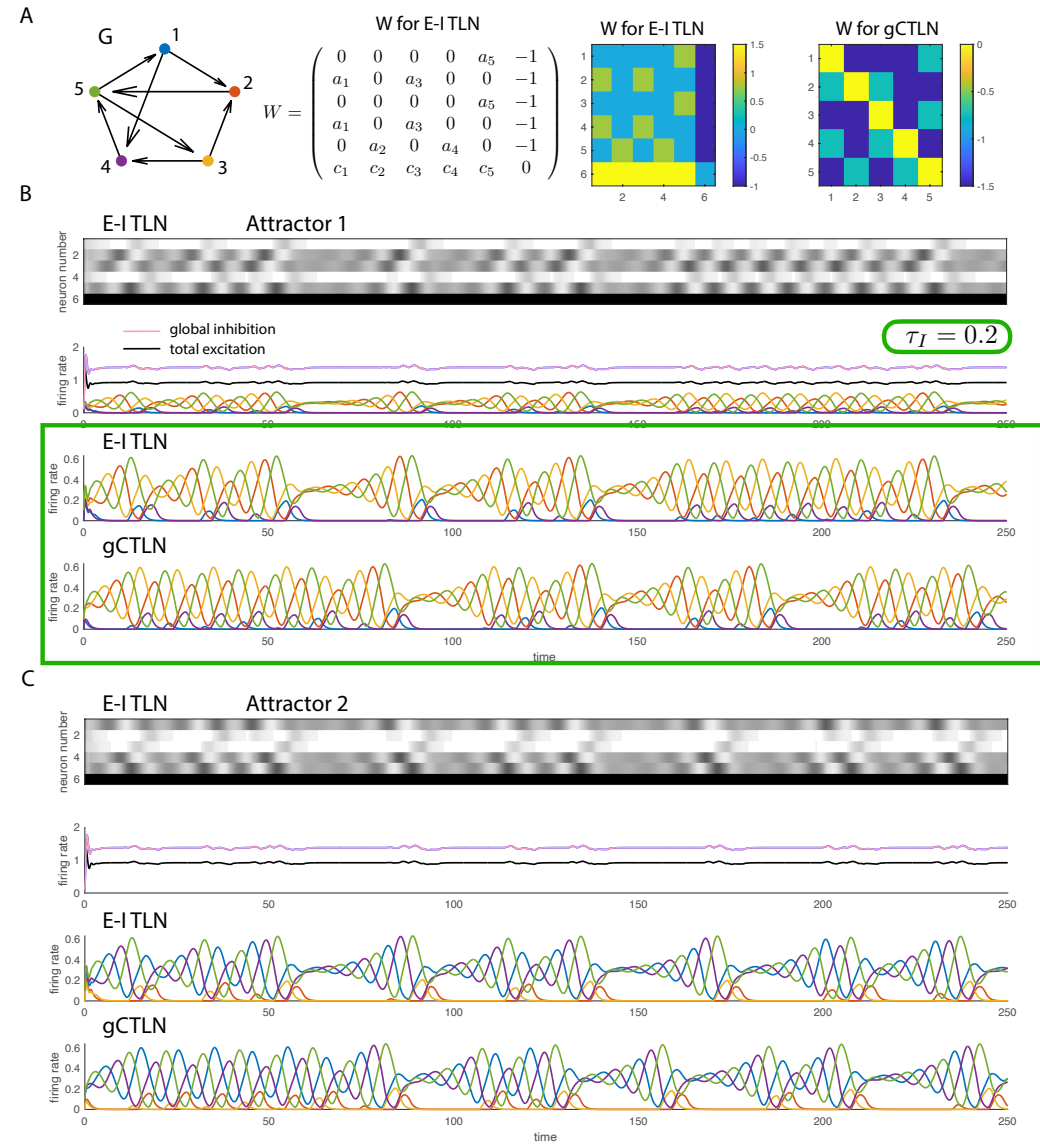
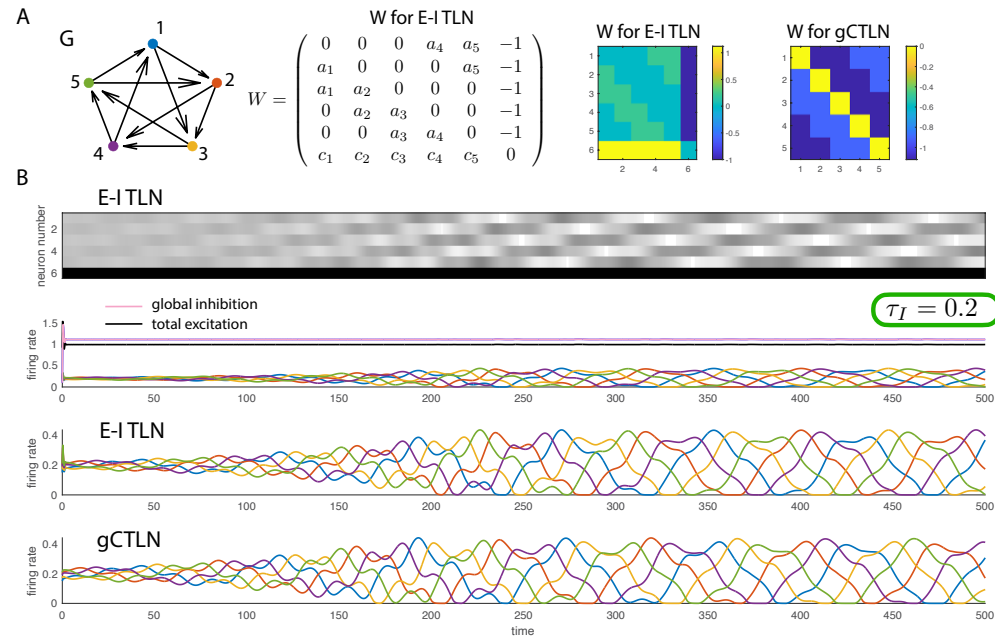
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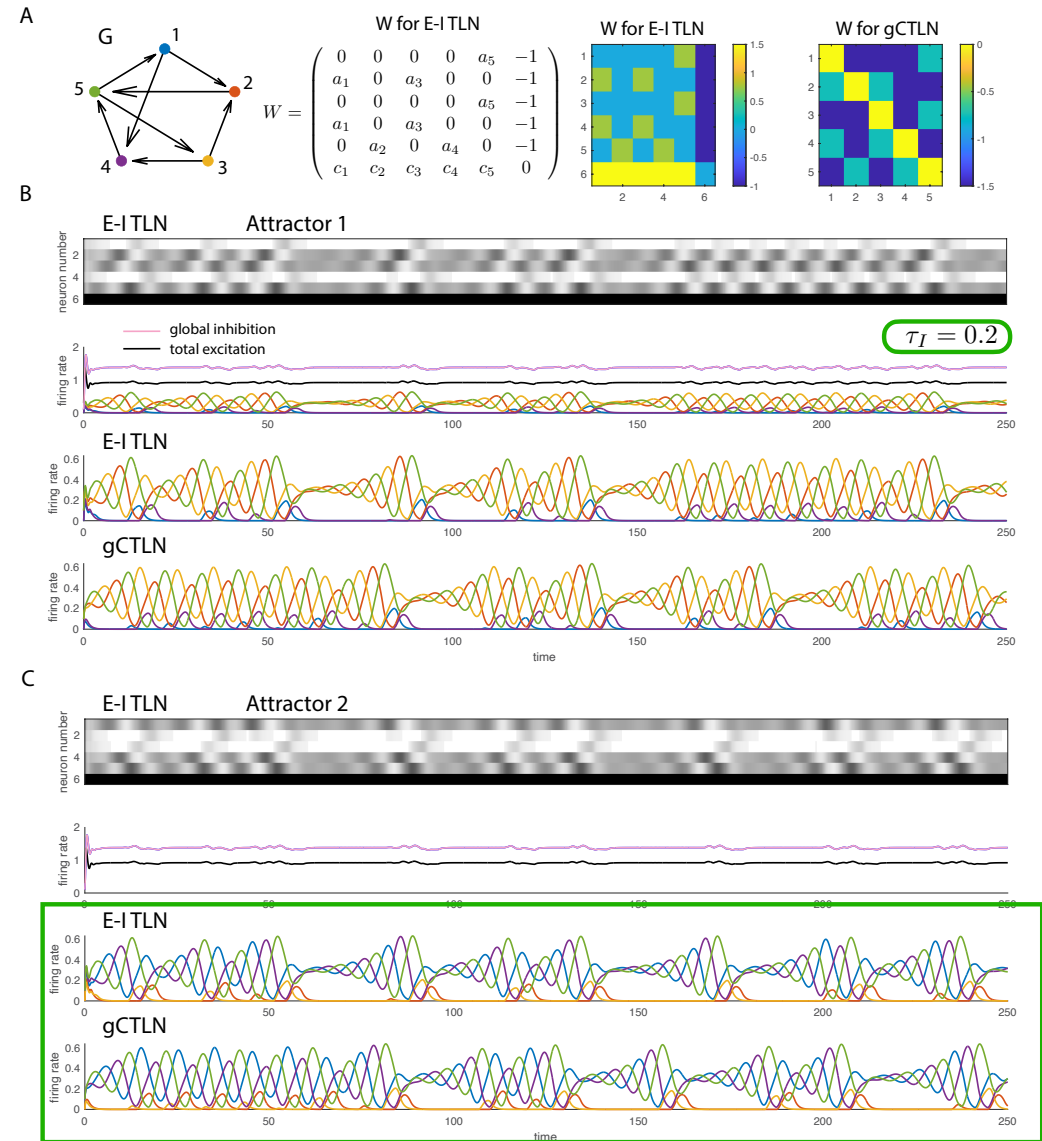
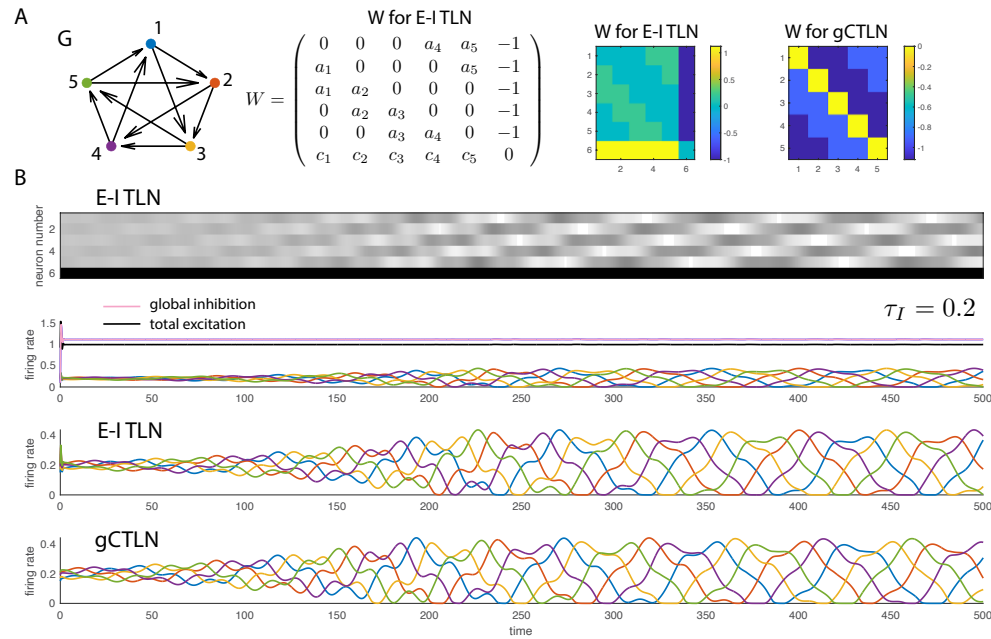
Even “exotic” attractors like Gaudi and baby chaos look the same



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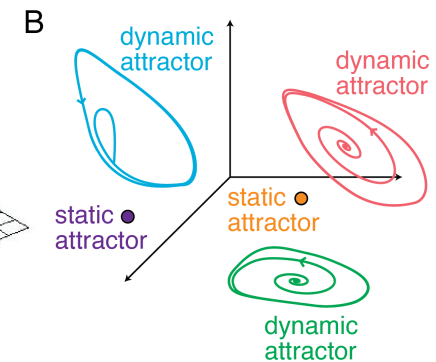
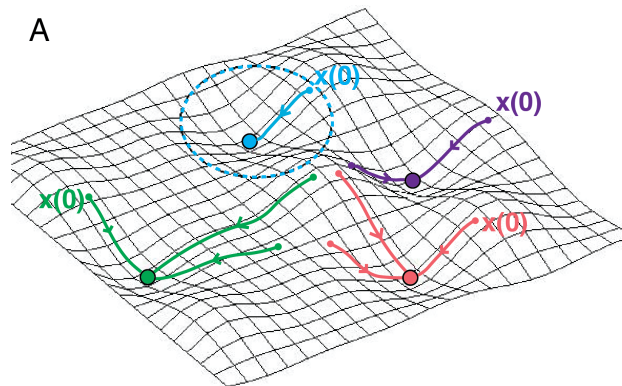
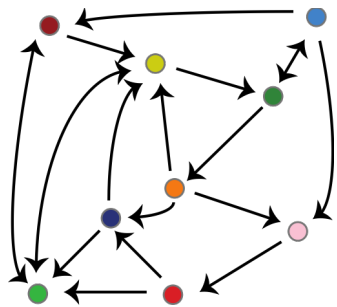


Even “exotic” attractors like Gaudi and baby chaos look the same



We had many mathematical results, called “graph rules” on CTLNs.

Now many of those results also apply to E-I TLNs built from graphs!



Domination Theorems

Theorem 1 (2024)

If j is a dominated node in G , then it drops out!

I.e., in any gCTLN, we have:

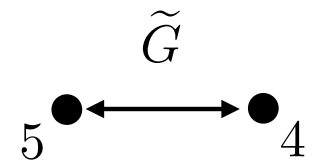
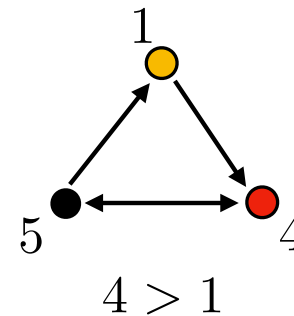
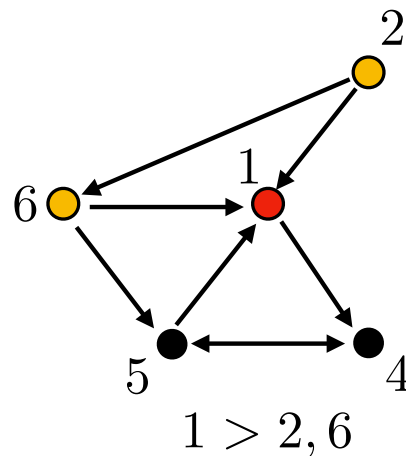
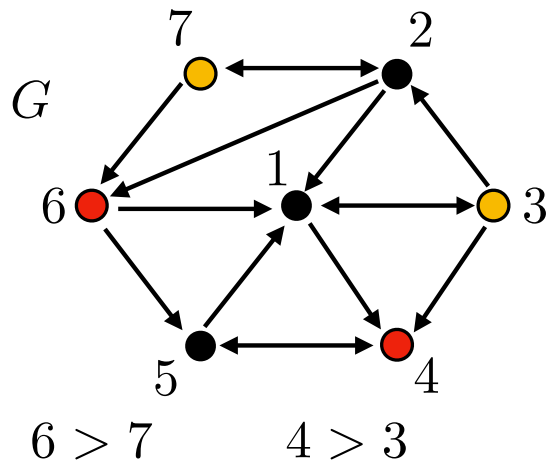
$$FP(G) = FP(G|_{[n] \setminus j})$$

Theorem 2 (2024)

By iteratively removing dominated nodes, the final reduced graph \tilde{G} is unique. Moreover,

$$FP(G) = FP(\tilde{G})$$

Example

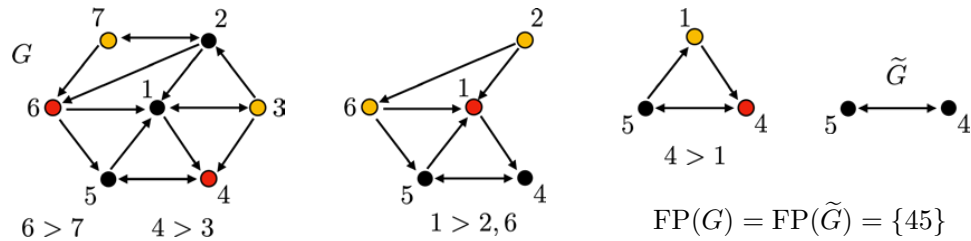


$$FP(G) = \{45\}$$

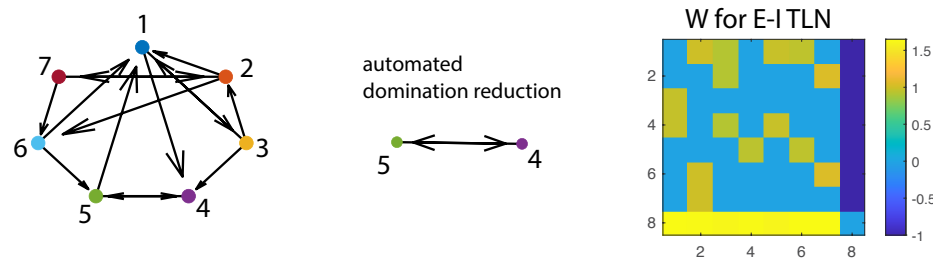
$$FP(\tilde{G}) = \{45\}$$

Since E-I TLNs map to gCTLNs with the same fixed points, the domination theorems hold for E-I TLNs, too!

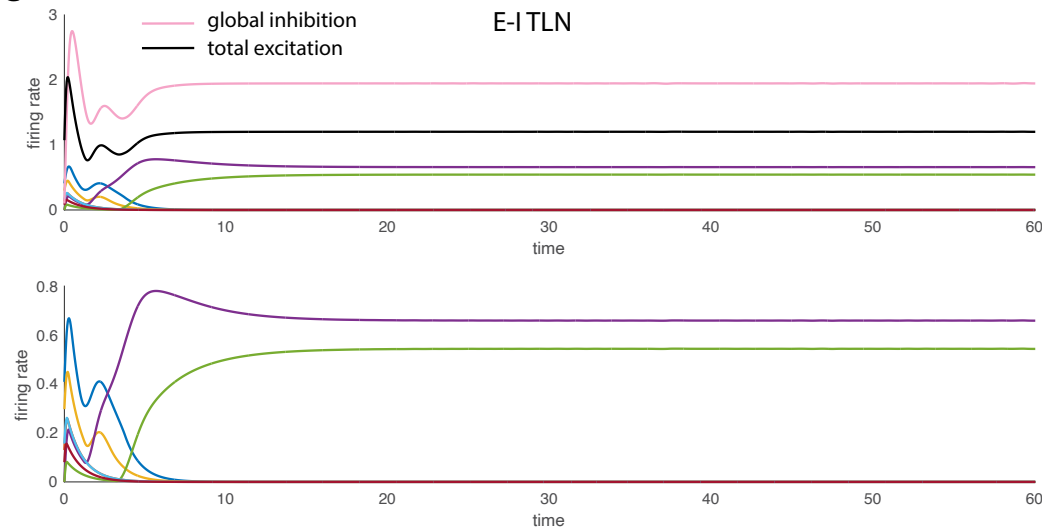
A



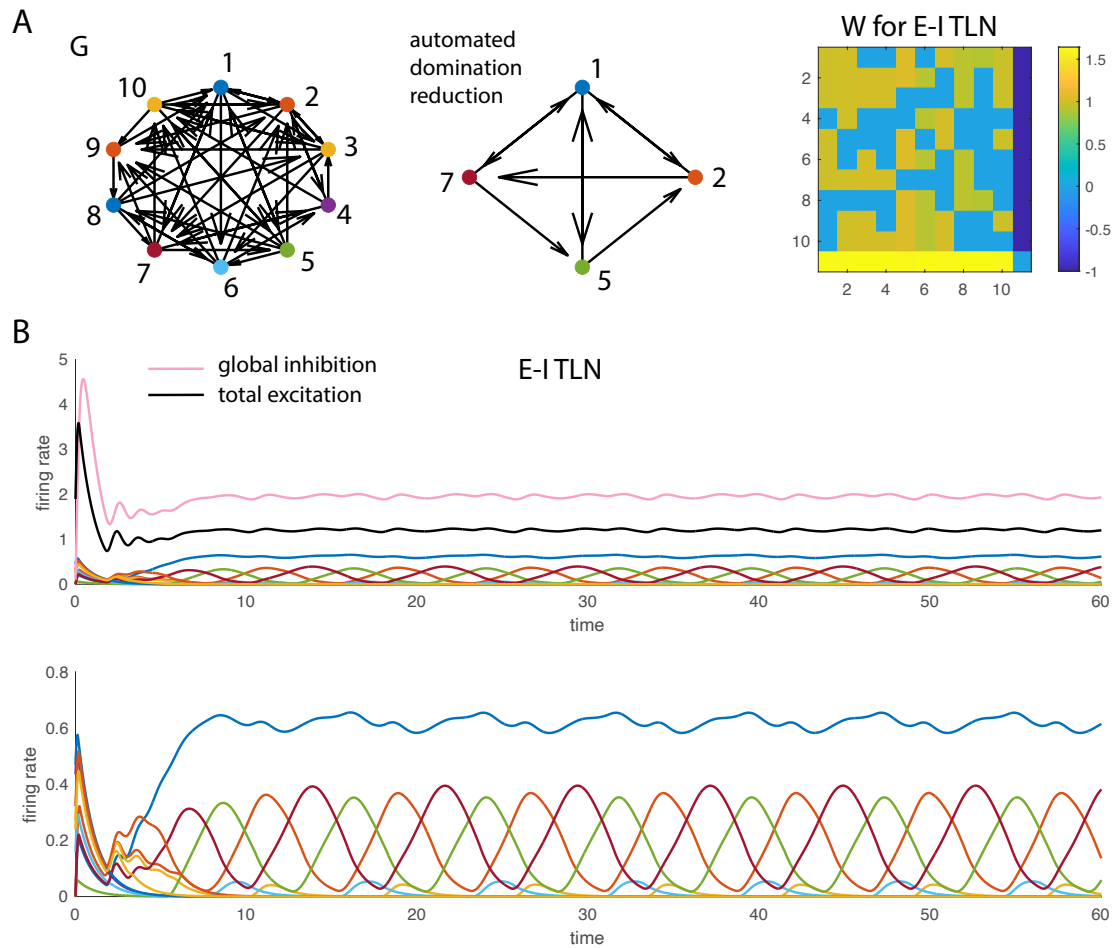
B



C

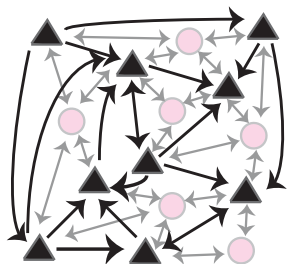


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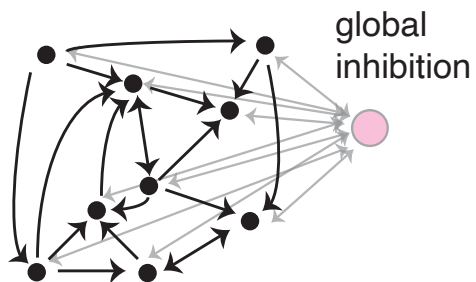


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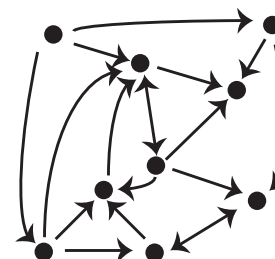
A excitatory neurons
in a sea of inhibition



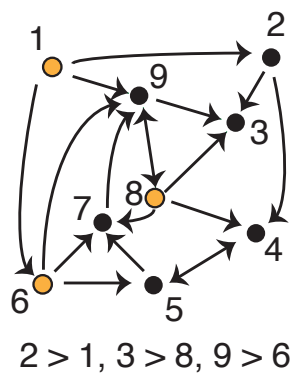
B E-I network



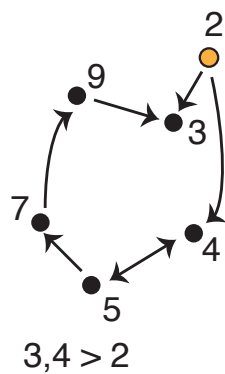
C graph G



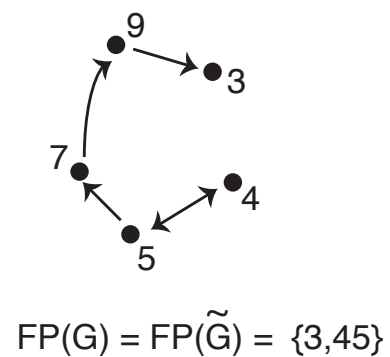
D domination in G



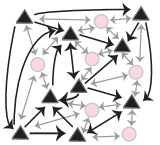
E partial reduction



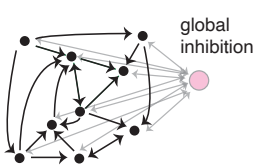
F reduced graph \tilde{G}



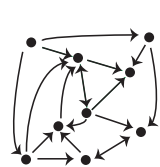
A excitatory neurons in a sea of inhibition



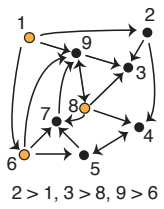
B E-I network



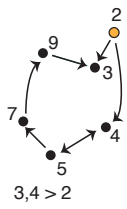
C graph G



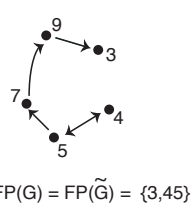
D domination in G



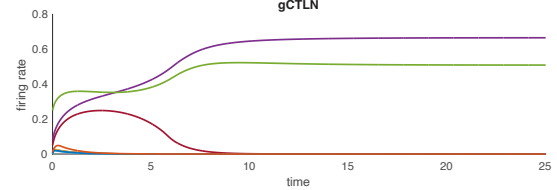
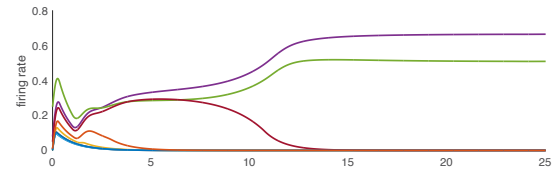
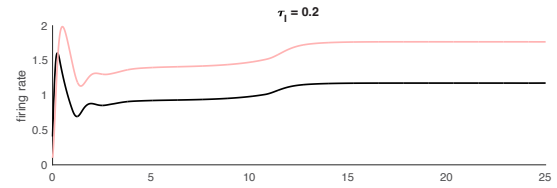
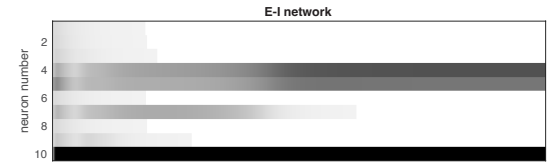
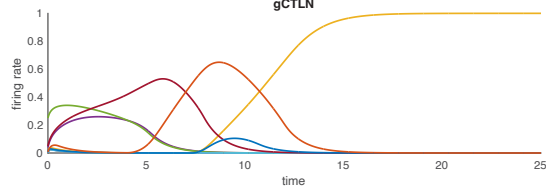
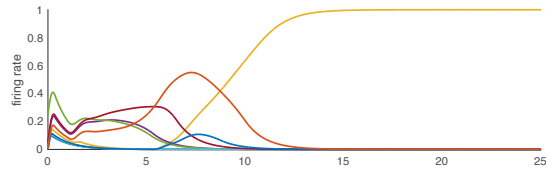
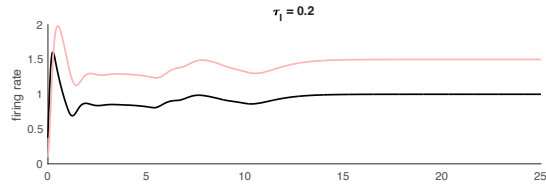
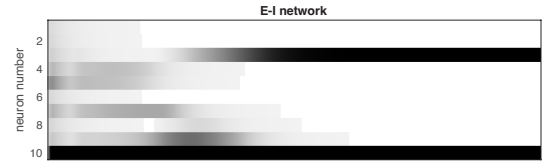
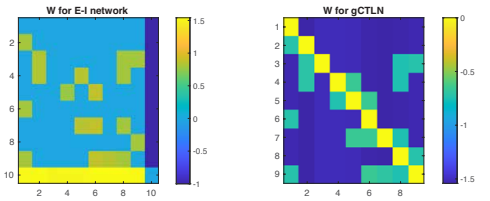
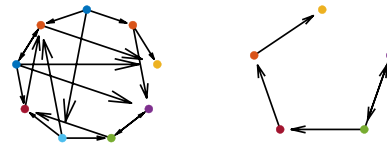
E partial reduction



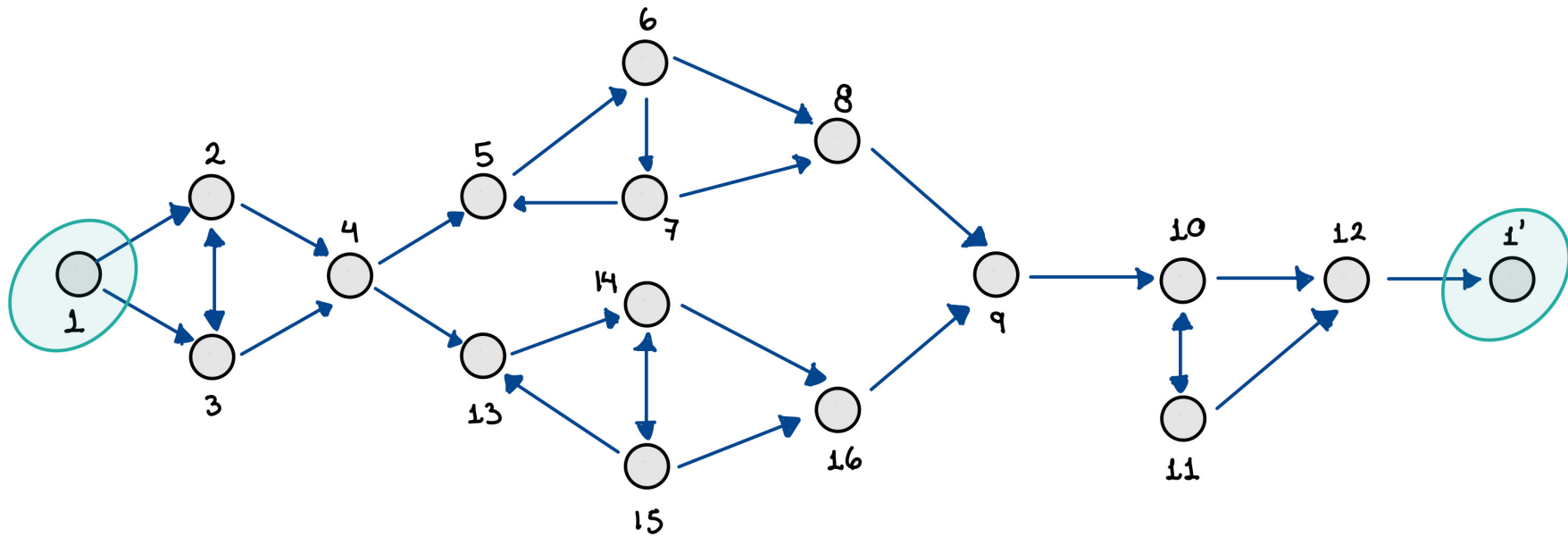
F reduced graph \tilde{G}



graph G reduced graph

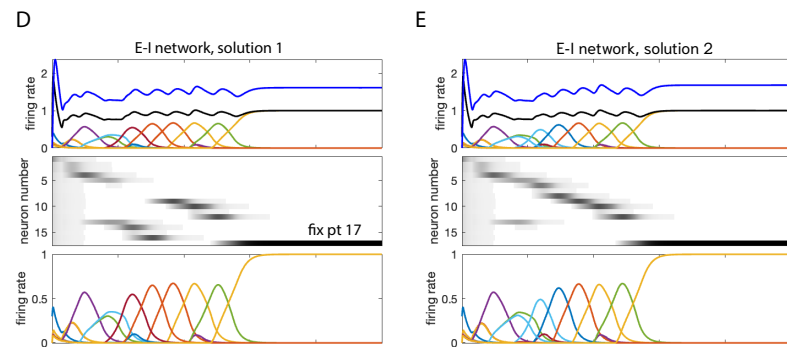
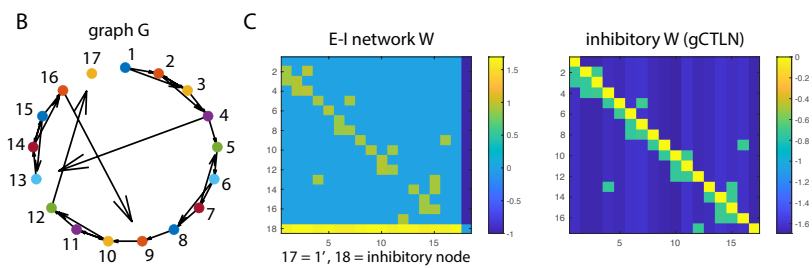
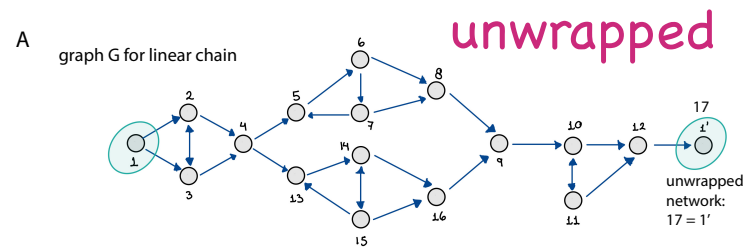


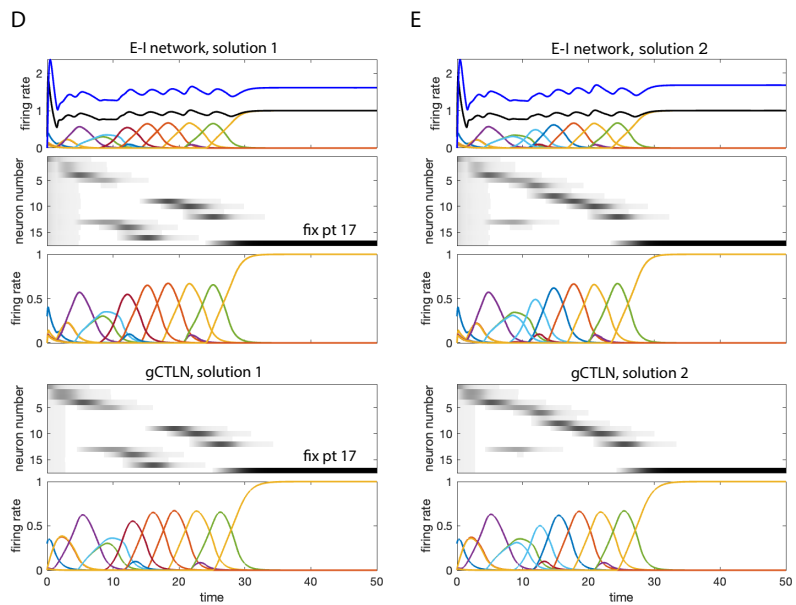
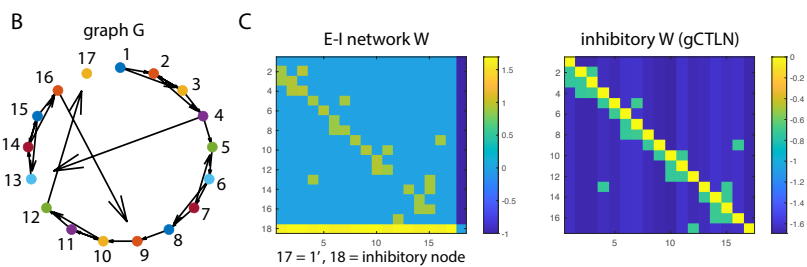
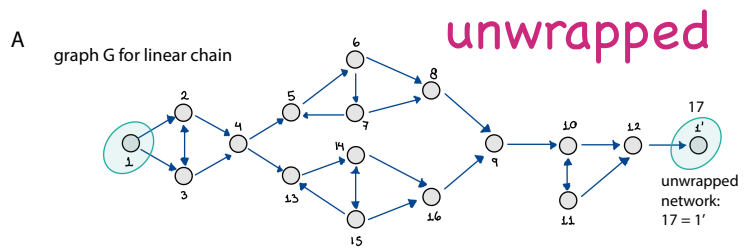
Cyclic chain example

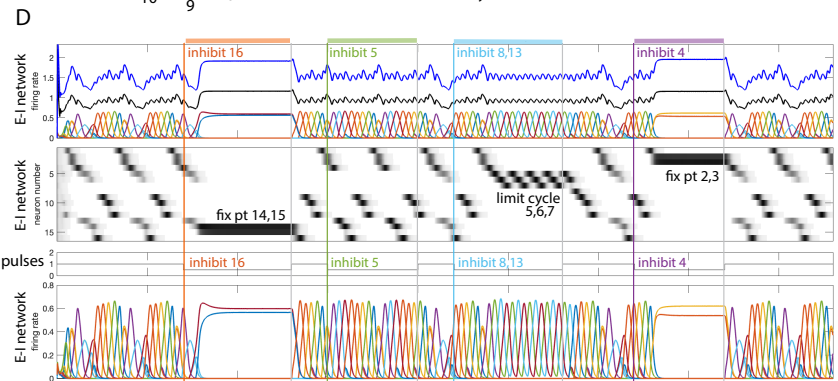
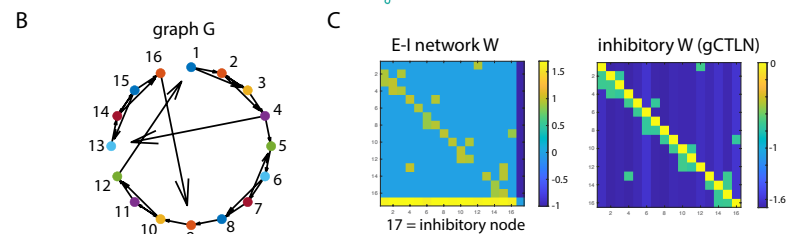
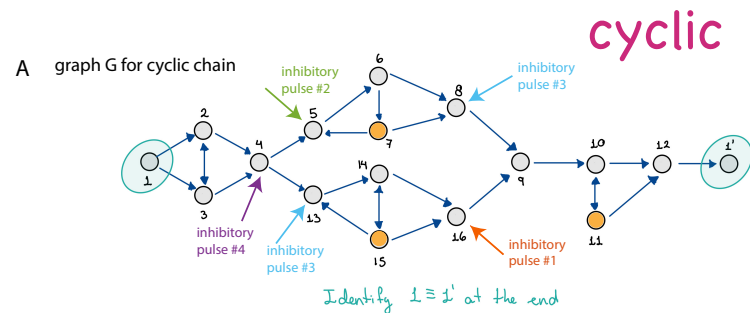
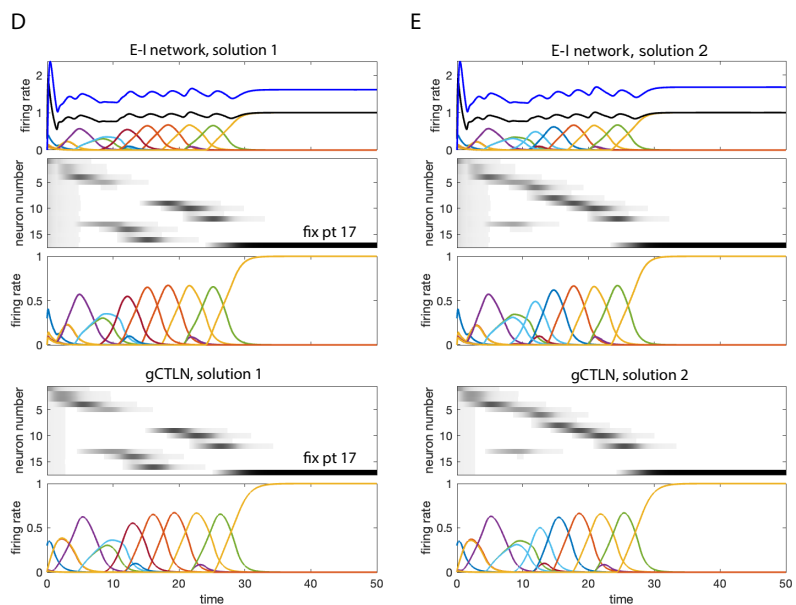
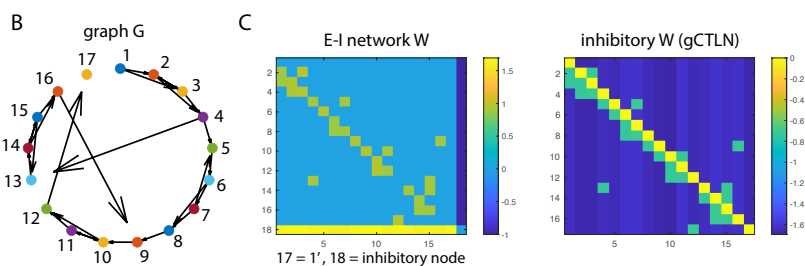
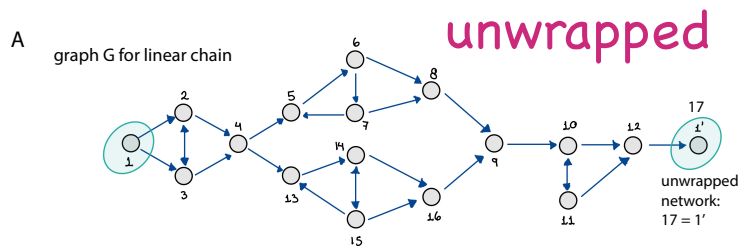


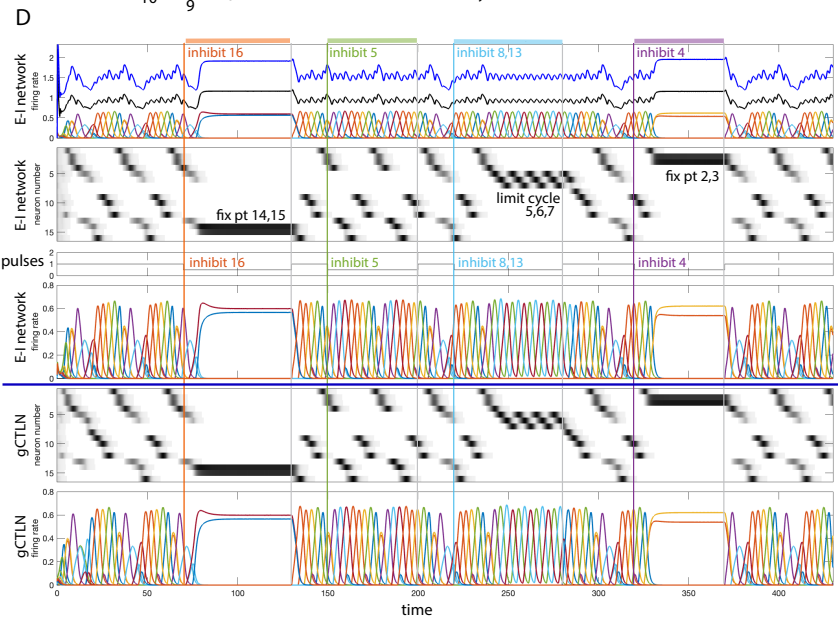
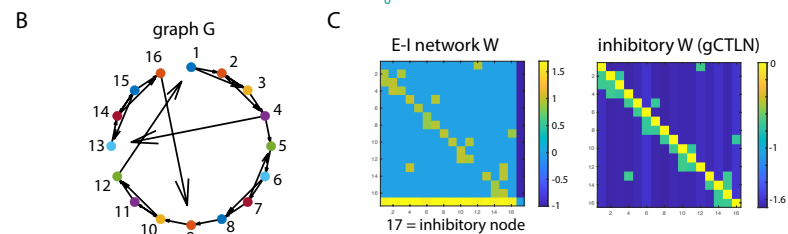
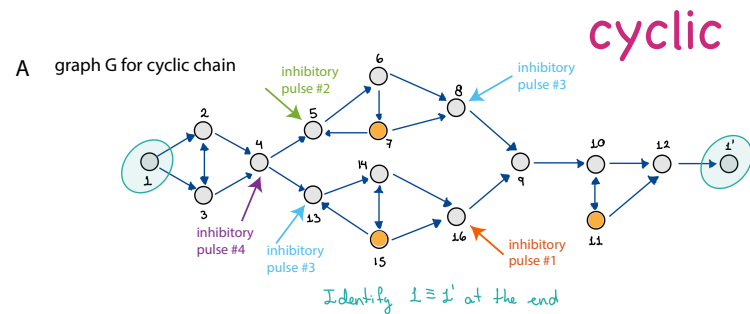
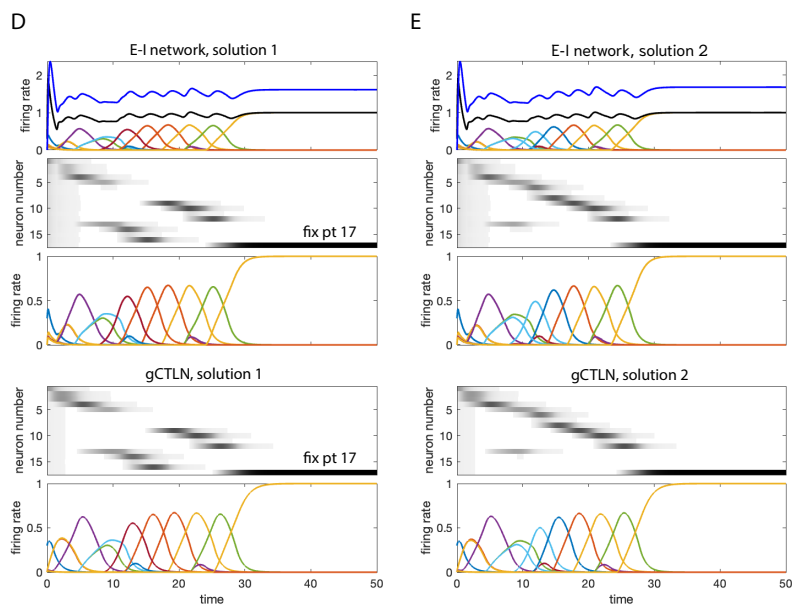
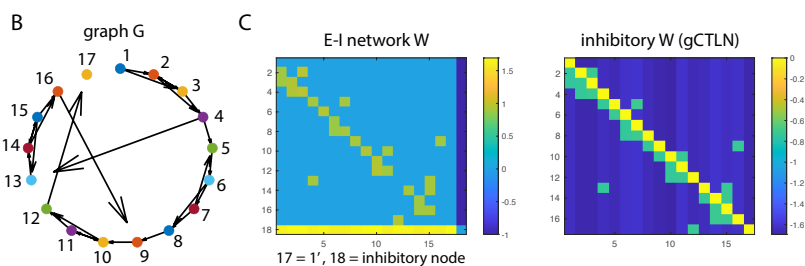
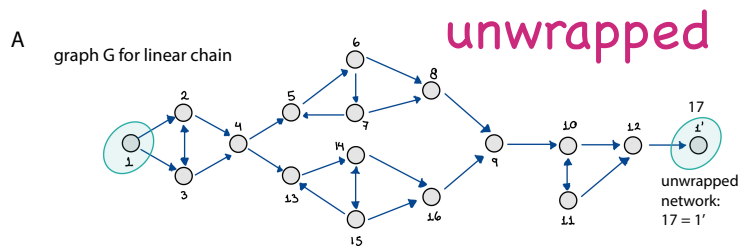
Identify $1 \equiv 1'$ at the end

Domination reduction cannot be done, and the network activity will loop around.

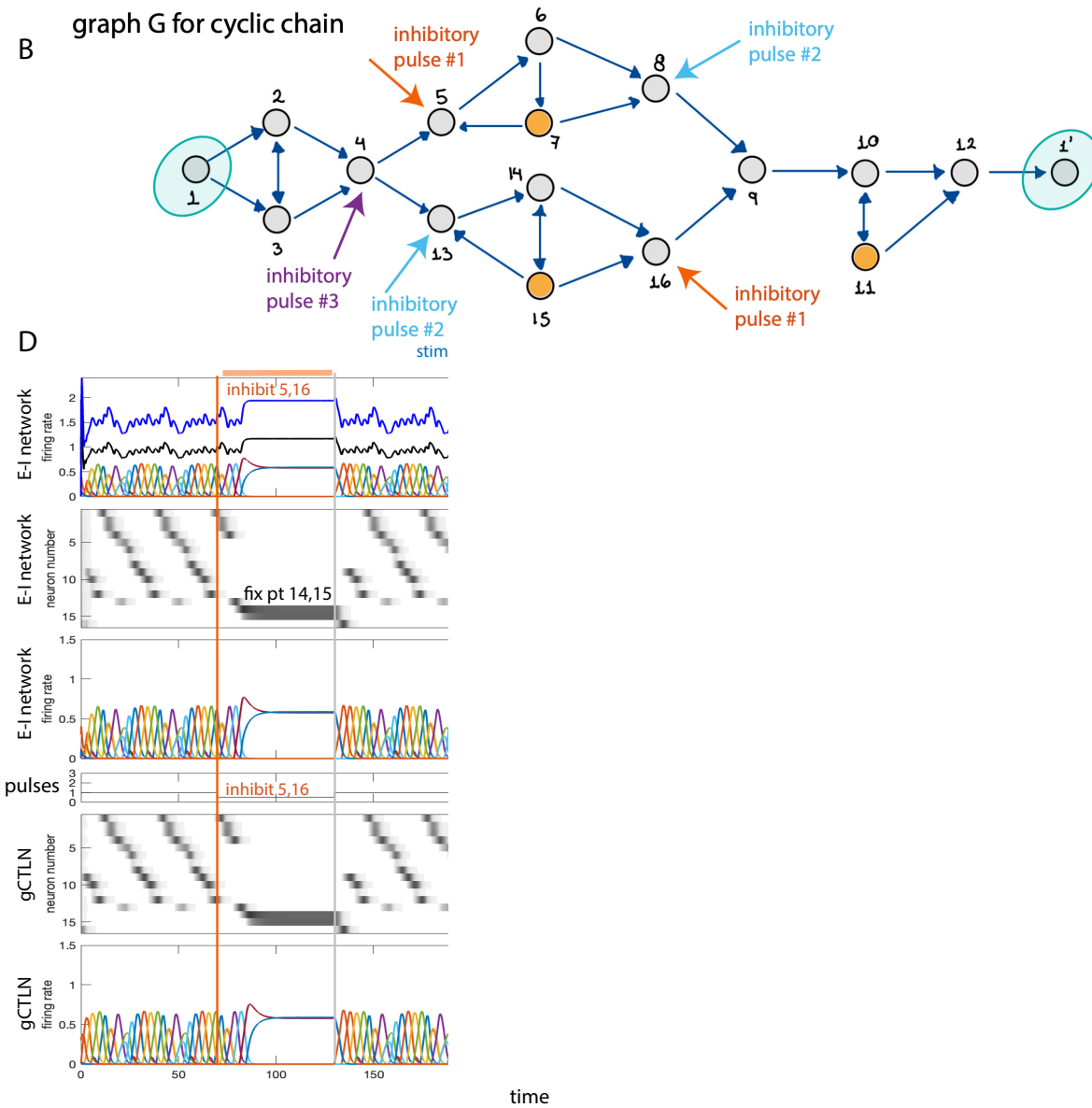






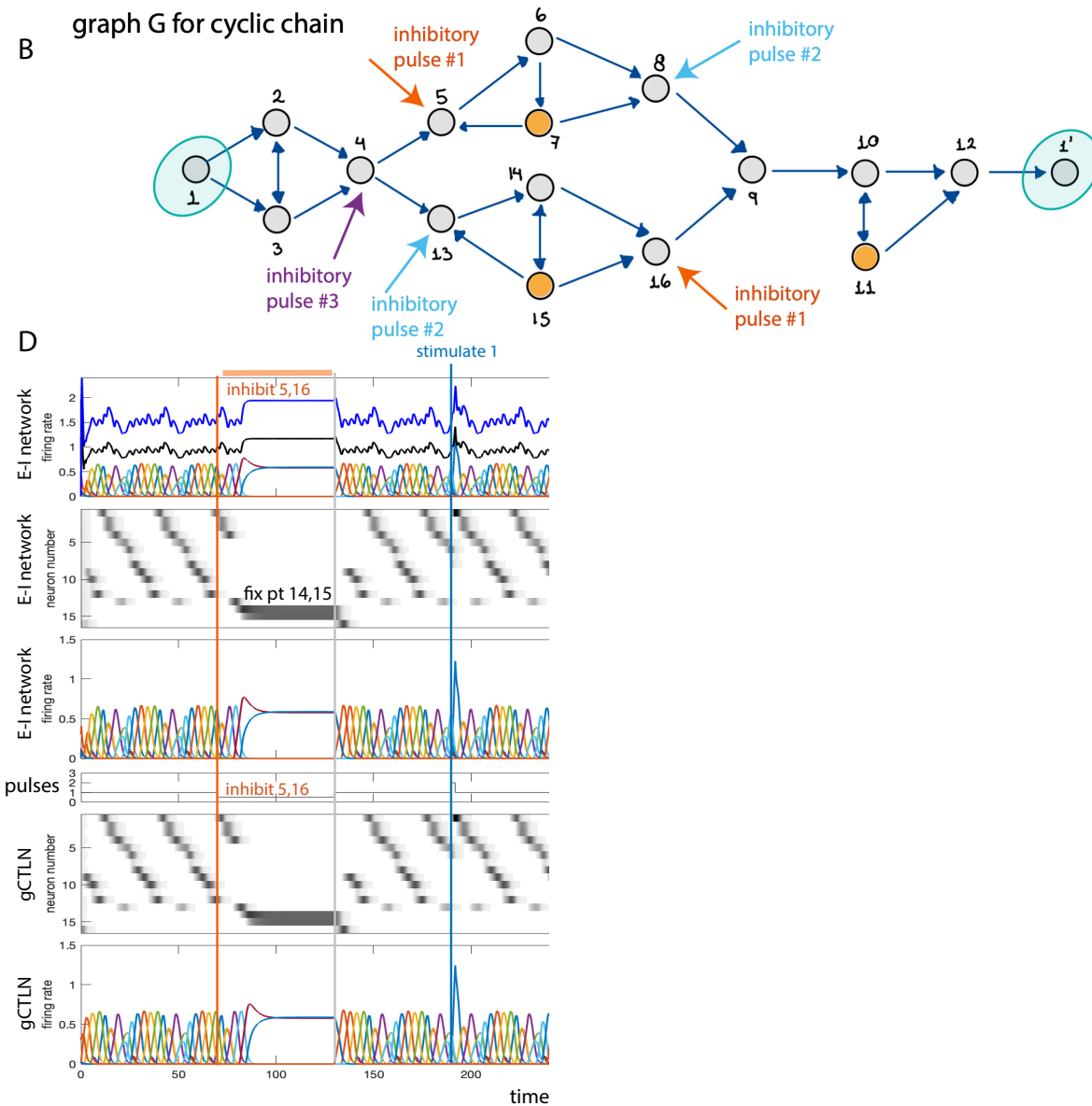


inhibitory pulses
= stop signs



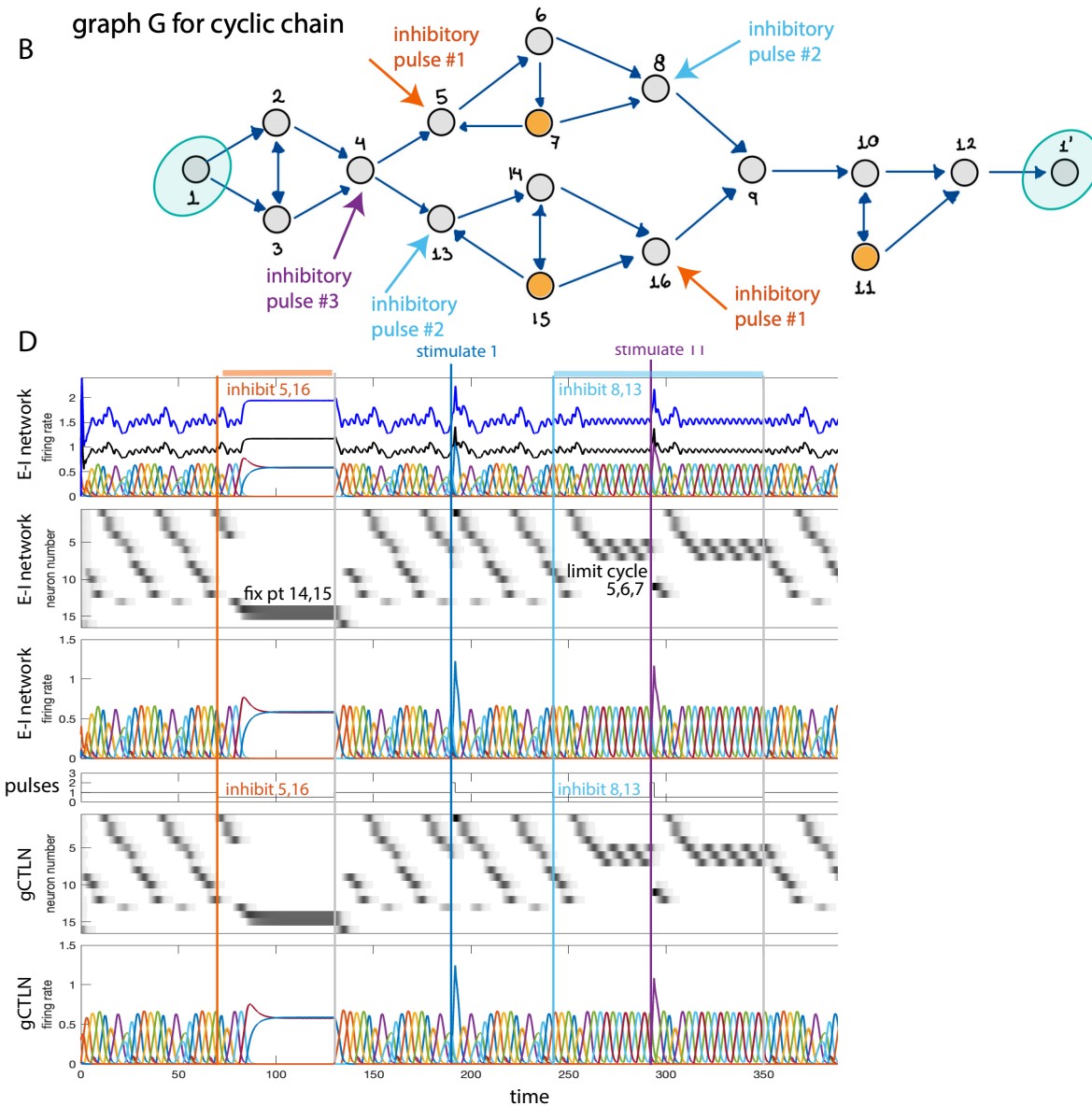
inhibitory pulses
= stop signs

excitatory pulses
= teleportation



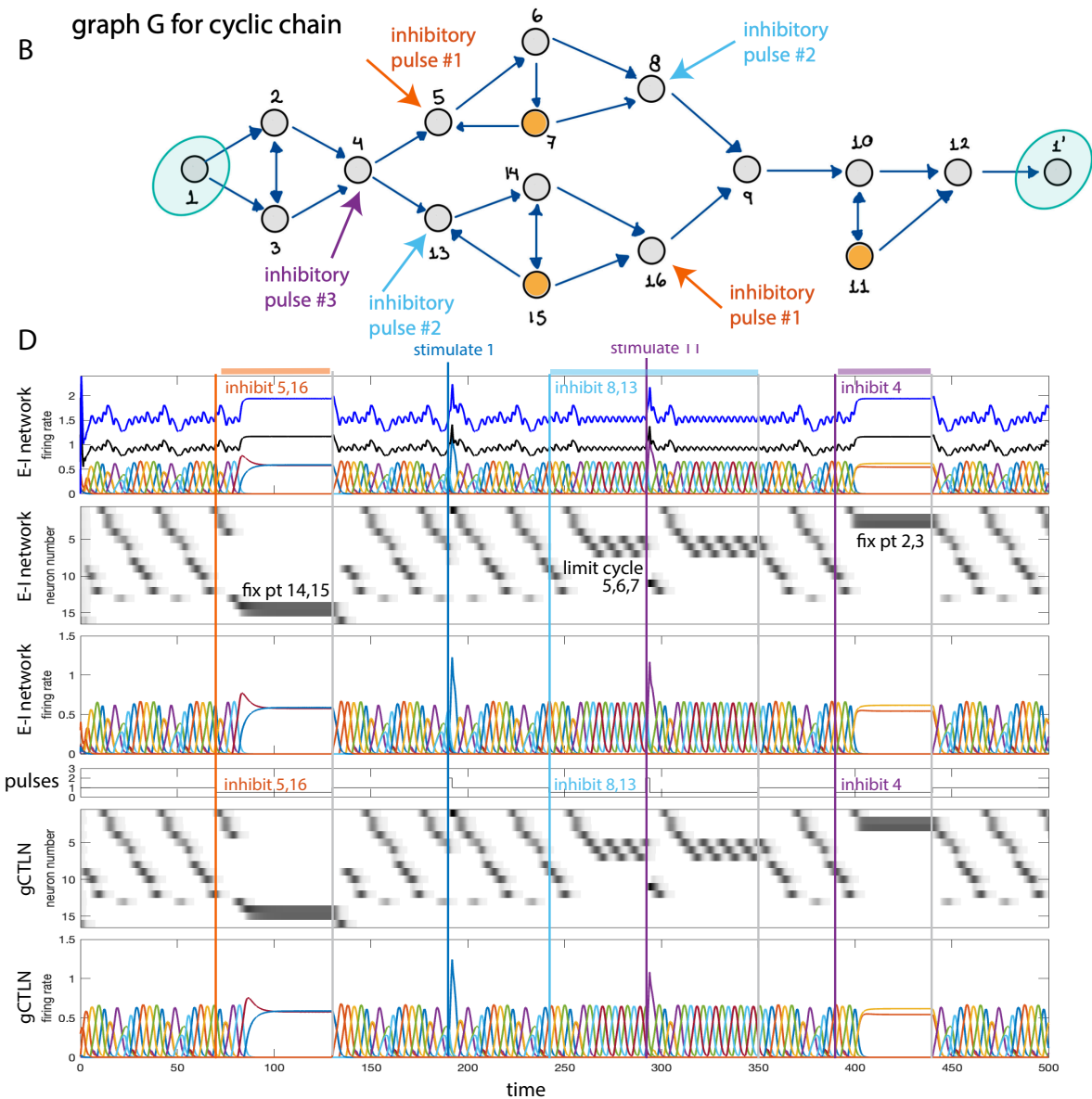
inhibitory pulses
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excitatory pulses
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inhibitory pulses
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excitatory pulses
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Thank you!



Katie Morrison



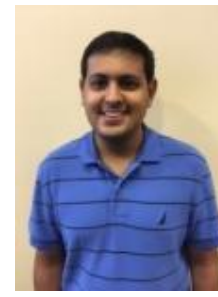
Caitlyn Parmelee



Chris Langdon



Nicole Sanderson



Safaan Sadiq



Jency (Yuchen) Jiang

grad student:
Zelong Li

Other Collaborators:



Jesse Geneson



Caitlin Lienkaemper



Juliana Londoño
Alvarez



Joaquín Castañeda Castro



Vladimir Itskov



Anda Degeratu

Jordan Matelsky (also at Penn)

Patricia Rivlin
Michael Robinette
Erik Johnson
Brock Wester

Johns Hopkins University Applied Physics Laboratory,
Research & Exploratory Development Department



Domination – New Theorems – a word about the proofs

3. Proof of Theorem 1.5 **Theorem 1**

In order to prove Theorem 1.5, it will be useful to use the notation

$$y_i(x) = \sum_{j=1}^n W_{ij}x_j + b_i. \quad (3.1)$$

With this notation, the equations for a TLN (W, b) become:

$$\frac{dx_i}{dt} = -x_i + [y_i(x)]_+.$$

If x^* is a fixed point of (W, b) , then $x_i^* = [y_i^*]_+$, where $y_i^* = y_i(x^*)$.

We can now prove the following technical lemma:

Lemma 3.2. *Let (W, b) be a TLN on n nodes and consider distinct $j, k \in [n]$. If $W_{ji} \leq W_{ki}$ for all $i \neq j, k$, and $b_j \leq b_k$, then for any fixed point x^* of (W, b) we have*

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Proof. Suppose x^* is a fixed point of (W, b) with support $\sigma \subseteq [n]$. Then, recalling that $W_{jj} = W_{kk} = 0$ and that $x_i^* = 0$ for all $i \notin \sigma$, from equation (3.1)

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The conditions in the theorem now immediately imply that $y_j^* - W_{jk}x_k^* \leq y_k^* - W_{kj}x_j^*$, and thus

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Lemma 3.5. *Suppose j is a dominated node in G . Then, for any associated gCTLN, $y_j^* \leq 0$ at every fixed point x^* (no matter the support).*

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need some more lemmas...

Lemma 3.6. *Let G be a graph with vertex set $[n]$. For any gCTLN on G ,*

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Proof of Theorem 1

Proof of Theorem 1.5. Suppose j is a dominated node in G , and let (W, b) be an associated gCTLN. By Lemma 3.5, we know that $y_j^* \leq 0$ at every fixed point (W, b) . It follows that $j \notin \sigma$ for all $\sigma \in \text{FP}(G)$. Hence,

$$\text{FP}(G) \subseteq \text{FP}(G|_{[n] \setminus \{j\}}).$$

It remains to show that $\text{FP}(G|_{[n] \setminus \{j\}}) \subseteq \text{FP}(G)$. By Lemma 3.6, this is equivalent to showing that for each $\sigma \in \text{FP}(G|_{[n] \setminus \{j\}})$, $\sigma \in \text{FP}(G|_{\sigma \cup \{j\}})$.

Suppose $\sigma \in \text{FP}(G|_{[n] \setminus \{j\}})$, with corresponding fixed point x^* . In this setting, we are not guaranteed that $y_j^* = y_j(x^*) \leq 0$, as x^* is not necessarily a fixed point of the full network. To see whether $\sigma \in \text{FP}(G|_{\sigma \cup \{j\}})$, it suffices to check the “off”-neuron condition for j : that is, we need to check if $y_j^* \leq 0$ when evaluating (3.1) at x^* .

Recall now that there exists a $k \in [n] \setminus \{j\}$ such that k graphically dominates j . It is also useful to evaluate y_k^* at x^* . Following the beginning of the proof of Lemma 3.2, we see that simply from the fact that $\text{supp}(x^*) = \sigma$, we obtain

$$y_j^* + W_{kj}x_j^* \leq y_k^* + W_{jk}x_k^*.$$

However, we cannot assume $x_j^* = [y_j^*]_+$, since we are not necessarily at a fixed point of the full network (W, b) . We know only that $x_j^* = 0$ and $x_k^* = [y_k^*]_+$, as the fixed point conditions are satisfied in the subnetwork $(W|_{[n] \setminus \{j\}}, b|_{[n] \setminus \{j\}})$ that includes k . This yields,

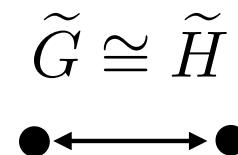
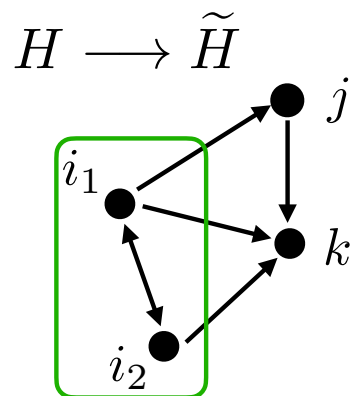
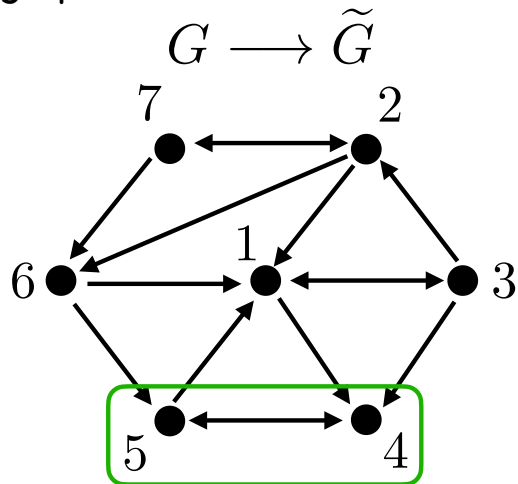
$$y_j^* \leq y_k^*(1 + W_{jk}) \leq 0,$$

where the second inequality stems from the fact that $W_{jk} < -1$. So, as it turns out, we see that $y_j^* \leq 0$ not only for fixed points of (W, b) , but also for fixed points from the subnetwork $(W|_{[n] \setminus \{j\}}, b|_{[n] \setminus \{j\}})$. We can thus conclude that $\text{FP}(G|_{[n] \setminus \{j\}}) \subseteq \text{FP}(G)$, completing the proof. \square

Can domination be useful for connectome analysis?

Every graph has a unique domination reduction: $G \longrightarrow \tilde{G}$

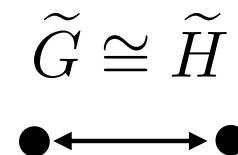
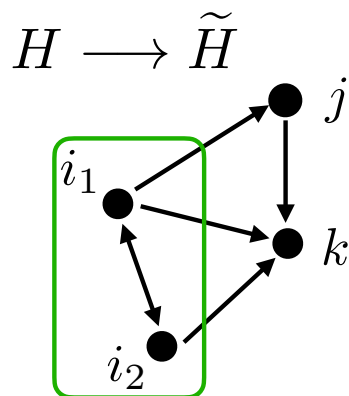
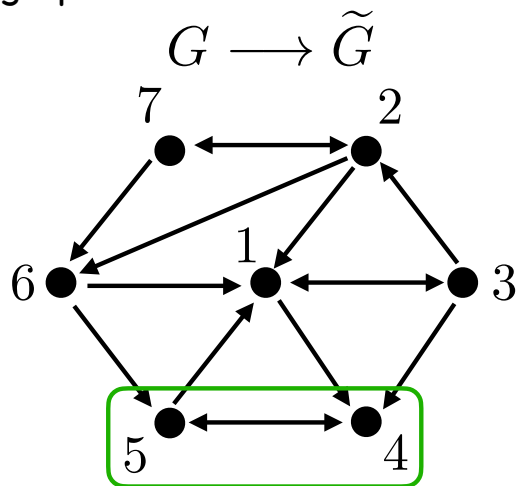
Two graphs with the same reduction are in the same domination equivalence class.



Can domination be useful for connectome analysis?

Every graph has a unique domination reduction: $G \longrightarrow \tilde{G}$

Two graphs with the same reduction are in the same domination equivalence class.



1. Are overrepresented graphical motifs more likely to be reducible or irreducible?
2. Which motifs are domination-equivalent?
3. What about larger portions of the connectome: do they reduce via domination?

Very preliminary analysis

Graph motifs team at JHU

Jordan Matelsky (also at Penn)

Patricia Rivlin

Michael Robinette

Erik Johnson

Brock Wester

Johns Hopkins University Applied Physics Laboratory,
Research & Exploratory Development Department



C. elegans E-E network:

G has 143 nodes

reduced G: 104 nodes



Joaquín Castañeda Castro

We first strip out everything but chemical synapses, then tag neurons by their small-molecule neurotransmitters—acetylcholine/ glutamate as excitatory, GABA as inhibitory—next we grab the induced subgraph of neurons that fire ACh/Glu but no GABA. That's our 'excitatory' network. And yes—it's just a conservative, transmitter-based proxy for valence; real C. elegans synaptic polarity is far messier (receptors, modulators, co-transmission, gap junctions, etc.) All blame goes to Jordan Matelsky, Carina did nothing wrong.

Very preliminary analysis

Is a reduction from 143 \rightarrow 104 nodes
common or rare in a random graph with
matching edge probability?



C. elegans E-E network:

G has 143 nodes

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Joaquín Castañeda Castro

Very preliminary analysis

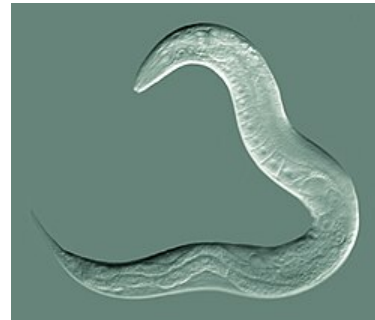
Is a reduction from 143 \rightarrow 104 nodes common or rare in a random graph with matching edge probability?

1 million E-R random graphs with matching $p = 0.054$

Distribution of domination reductions:

- 143 nodes: 782,590
- 142 nodes: 189,951
- 141 nodes: 24,951
- 140 nodes: 2,307
- 139 nodes: 185
- 138 nodes: 15
- 137 nodes: 1

VERY RARE!!



C. elegans E-E network:

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Joaquín Castañeda Castro

C. elegans E-E network
reduction:

G has 143 nodes

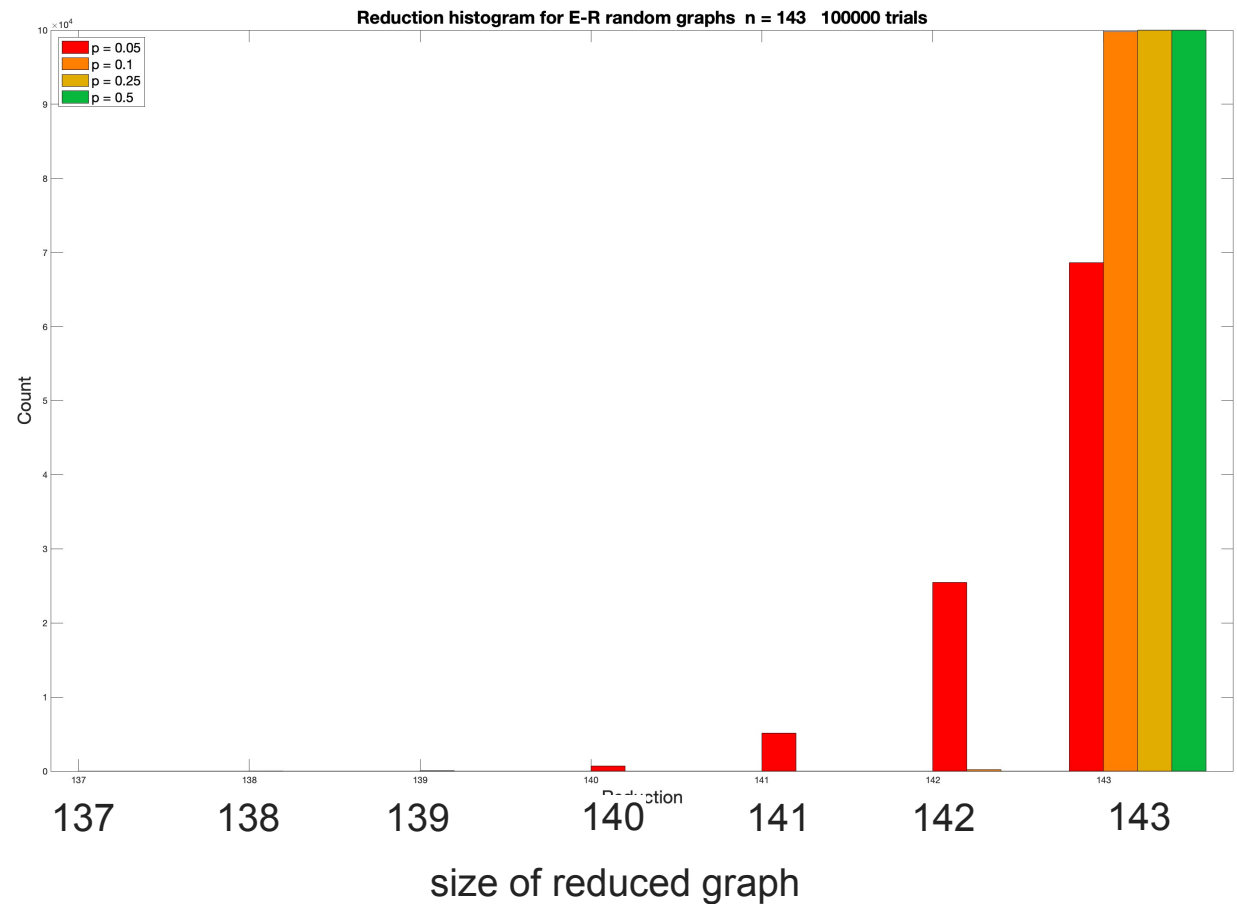
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Reduction sizes of E-R random graphs of size $n=143$
with $p = 0.05, 0.1, 0.25, 0.5$



Back to our motivating questions and ideas:

1. How does connectivity shape dynamics?
2. The relationship between connectivity and neural activity depends on the dynamical system you associate to the connectome.
3. By studying neuroscience-inspired (nonlinear!) dynamical systems on graphs, we can generate hypotheses about the dynamic meaning/role of various network motifs.

Domination is a graph property that comes out of the nonlinear dynamics, it is not something that graph theorists or network scientists were already paying attention to.

